

Minimum cost design for circular isolated footings with eccentric column taking into account that the surface in contact with the ground works partially in compression

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Abstract. This work aims to show a model to estimate the minimum cost (Thickness and area of steel in X and Y directions) for design a circular isolated footing with eccentric column that considers that the surface in contact with the ground works partially under compression. The formulation is shown by integration to find the moments, the bending shears and the punching shear using the pressure volume under the footing. Some researchers show the minimum cost design for circular isolated footings for an eccentric column assuming that the contact area works completely in compression, others consider the contact surface with the ground working partially in compression for a column in the center of the base. Three numerical examples are developed to obtain the complete design, which are: Example 1 for a column in the center of the base, Example 2 for a column at a distance of 1.50 m from the center of the base in the X direction, Example 3 for a column at a distance of 1.50 m from the center of the base in both directions. Also, a comparison of the new model against the model proposed by other authors is presented. The comparison shows that the new model generates a great saving of up to 43.74% for minimum area and 48.44% for minimum cost design in a column located in the center of the base, and when the column is located at a distance of radius/2 starting from the center of the base in the X direction generates great savings of up to 45.24% for minimum area and 31.80% for minimum cost design. Therefore, it is advisable to use the model presented in this study.

Keywords: bending shears; circular isolated footings; minimum cost design; moments; punching shear; surface in contact with the ground works partially under compression

1. Introduction

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A foundation is the support base of the entire structure through which loads are transmitted to the underlying soil. Every foundation must permanently guarantee the stability of the construction it supports.

The main contributions on the bearing capacity of the soil, soil-structure interaction, experimental tests for footings and settlement behavior in foundations under biaxial bending have been presented by several researchers (Ramu and Madhav 2010, Lee *et al.* 2015, Kaur and Kumar 2016, Dagdeviren 2016, Hadzalic *et al.* 2018a, b, c, 2020, Turedi *et al.* 2019, Golewski 2019, Luat *et al.* 2020, Ibrahimbegovic *et al.* 2021).

The most relevant references that address the topic of foundation design, mathematical models for the design and contact surface with the ground for all types of foundations have been presented in the work proposed by Luévanos-Soto *et al.* (2024) (Agrawal and Hora 2012, Aguilera-Mancilla *et al.* 2019, Al-Ansari 2013, 2014, Alijani and Bidgoli 2018, Alazwari *et al.* 2021, Anil *et al.* 2017, Basudhar *et al.* 2012, Garay-Gallegos *et al.* 2022, García-Galván *et al.* 2022a, b, Garcia-Graciano *et al.* 2022, Gör 2022, Himeur *et al.* 2022, Jelusic and Zlender 2018, Khajehzadeh *et al.* 2014, Kim-Sanchez *et al.* 2022, Lezgy-Nazargah *et al.* 2022, López-Chavarría *et al.* 2017a, b, c, 2019, Luévanos-Rojas 2014a, b, c, 2015a, b, 2016a, b, c, 2023a, b, c, Luévanos-Rojas *et al.* 2013, 2017a, b, 2018a, b, 2020, 2022, 2024a, Malapur *et al.*, 2018, Mohebkah 2017, Montes-Páramo *et al.* 2023, Moreno-Hernández *et al.* 2022, Pasillas-Orona *et al.* 2020, Rad 2012, Rawat and Mittal 2018, Rivera-Mendoza *et al.* 2022, Rizwan *et al.* 2012, Soto-García *et al.* 2022, Vela-Moreno *et al.* 2022, Velázquez-Santillán *et al.* 2018, Yáñez-Palafox *et al.* 2019).

The current studies closest to the topic of isolated footings are: The minimum cost design assuming that the contact zone with the ground works partially in compression for circular footings proposed by Kim-Sánchez *et al.* (2022) and for rectangular footings investigated by Luévanos-Rojas (2023c), but in these works the column is in the center of the base. The minimum cost design with an eccentric column for rectangular footings (Luévanos-Rojas 2023a) and for circular footings (Luévanos-Rojas *et al.* 2024b), but in these works present the contact zone with the ground working completely under compression.

This study shows a model to estimate the minimum cost design (Thickness and areas of steel in X and Y directions) for circular isolated footings with an eccentric column taking into account that the contact area with the ground works partially in compression, that is, a part of the contact area of the footing is under compression and the other under zero pressure. The formulation is presented by integration to find the factored moments, the factored bending shears and the factored punching shear using the pressure volume under the footing in function of the factored available allowable soil pressure, the radius of the circular footing, the angle of inclination with respect to the Y axis where the resultant moment appears, the location coordinates of the column, the distance from the center of the base to the neutral axis measured on the axis where the resultant moment appears, the sides of the column. Three numerical problems are given to estimate the minimum cost design for circular isolated footings under biaxial bending. In addition, a comparison is made between the new model and the model proposed by other authors to observe the differences.

2. Methodology

2.1 Case I: Area works completely under compression

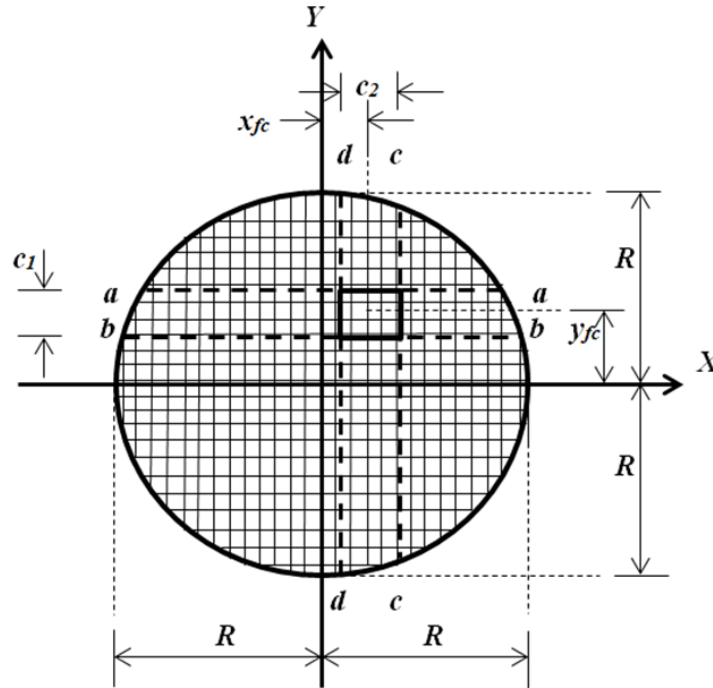


Fig. 1 Moments in the critical sections for an circular isolated footing with eccentric column

The general equation to estimate the soil pressure on the footing due to the factored loads and moments is (Luévanos-Rojas *et al.* 2024b)

$$\sigma_u(x, y) = \frac{P_u}{\pi R^2} + \frac{4(M_{xu} + P_u y_{fc})y}{\pi R^4} + \frac{4(M_{yu} + P_u x_{fc})x}{\pi R^4} \quad (1)$$

where: σ_u is the factored soil pressure on the footing (kN/m^2), R is the radius of the circular base (m), x_{fc} and y_{fc} are the coordinates where the column is located (m), x and y are the coordinates in the X and Y directions of the base (m), P_u is the factored axial load (kN)= $1.2P_D$ (Dead load)+ $1.6P_L$ (Live load), M_{xu} is the factored moment on the X axis (kN-m)= $1.2M_{xD}$ (Dead load moment on the X axis)+ $1.6M_{xL}$ (Live load moment on the X axis), M_{yu} is the factored moment on the Y axis (kN-m)= $1.2M_{yD}$ (Dead load moment on the Y axis)+ $1.6M_{yL}$ (Live load moment on the Y axis) (ACI 318S-14 2014).

2.1.1 Factored moments

Fig. 1 presents the critical sections for the moments. The moments to be obtained in the critical sections appear on the a , b , c and d axes.

The moments M_{au} on the a axis, M_{bu} on the b axis, M_{cu} on the c axis, and M_{du} on the d axis are obtained by Luévanos-Rojas *et al.* (2024b)

$$M_{au} = - \int_{y_{fc} + \frac{c_1}{2}}^R \int_{-\sqrt{R^2 - y^2}}^{\sqrt{R^2 - y^2}} \sigma_u \left(y - y_{fc} - \frac{c_1}{2} \right) dx dy \quad (2)$$

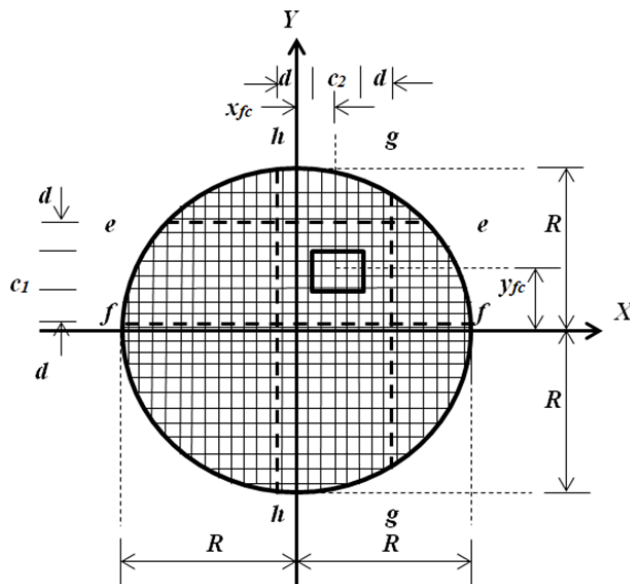


Fig. 2 Bending shears in the critical sections for a circular isolated footing with eccentric column

$$M_{bu} = \frac{P_u c_1}{2} + M_{xu} - \int_{y_{fc} - \frac{c_1}{2}}^R \int_{-\sqrt{R^2 - y^2}}^{\sqrt{R^2 - y^2}} \sigma_u \left(y - y_{fc} + \frac{c_1}{2} \right) dx dy \quad (3)$$

$$M_{cu} = - \int_{x_{fc} + \frac{c_2}{2}}^R \int_{-\sqrt{R^2 - x^2}}^{\sqrt{R^2 - x^2}} \sigma_u \left(x - x_{fc} - \frac{c_2}{2} \right) dy dx \quad (4)$$

$$M_{du} = \frac{P_u c_2}{2} + M_{yu} - \int_{x_{fc} - \frac{c_2}{2}}^R \int_{-\sqrt{R^2 - x^2}}^{\sqrt{R^2 - x^2}} \sigma_u \left(x - x_{fc} + \frac{c_2}{2} \right) dy dx \quad (5)$$

where: c_1 is the side of the column in the Y direction (m), c_2 is the side of the column in the X direction (m).

2.1.2 Factored bending shears

Fig. 2 shows the critical sections for bending shears. The bending shears to be obtained in the critical sections appear on the e , f , g and h axes.

The bending shears V_{eu} on the e axis, V_{fu} on the f axis, V_{gu} on the g axis, and V_{hu} on the h axis are obtained by Luévanos-Rojas *et al.* (2024b)

$$V_{eu} = - \int_{y_{fc} + \frac{c_1}{2} + d}^R \int_{-\sqrt{R^2 - y^2}}^{\sqrt{R^2 - y^2}} \sigma_u dx dy \quad (6)$$

$$V_{uf} = P_u - \int_{y_{fc} - \frac{c_1}{2} - d}^R \int_{-\sqrt{R^2 - y^2}}^{\sqrt{R^2 - y^2}} \sigma_u dx dy \quad (7)$$

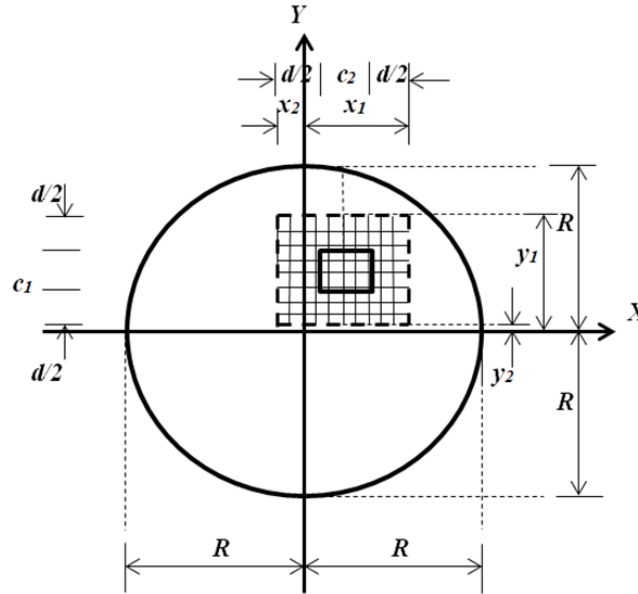


Fig. 3 Punching shear in the critical perimeter for an circular isolated footing with eccentric column

$$V_{gu} = - \int_{x_{fc} + \frac{c_2}{2} + d}^R \int_{-\sqrt{R^2 - x^2}}^{\sqrt{R^2 - x^2}} \sigma_u dy dx \tag{8}$$

$$V_{hu} = P_u - \int_{x_{fc} - \frac{c_2}{2} - d}^R \int_{-\sqrt{R^2 - x^2}}^{\sqrt{R^2 - x^2}} \sigma_u dy dx \tag{9}$$

2.1.3 Factored punching shear

Fig. 3 shows the critical perimeter for the punching shear. The punching shear to be obtained in the critical perimeter appears on the Y direction from y_2 to y_1 and in the X direction from x_2 to x_1 .

The punching shear V_{eu} on the critical perimeter is obtained by Luévanos-Rojas *et al.* (2024b)

$$V_{pu} = P_u - \int_{y_2}^{y_1} \int_{x_2}^{x_1} \sigma_u dx dy \tag{10}$$

where: $y_2 = y_{fc} - c_1/2 - d/2$, $y_1 = y_{fc} + c_1/2 + d/2$, $x_2 = x_{fc} - c_2/2 - d/2$, $x_1 = x_{fc} + c_2/2 + d/2$ (When the critical perimeter is located inside the footing), When the critical perimeter is located in a portion outside the footing, the perimeter that is located inside the footing must be considered.

2.2 Case II: Area works partially under compression

The general equation to estimate the soil pressure on the footing due to the factored maximum pressure is obtained (Luévanos-Soto *et al.* 2024)

$$\sigma_z(x, y) = \frac{\sigma_{u\max}(x \sin \alpha + y \cos \alpha - y_0)}{(R - y_0)} \tag{11}$$

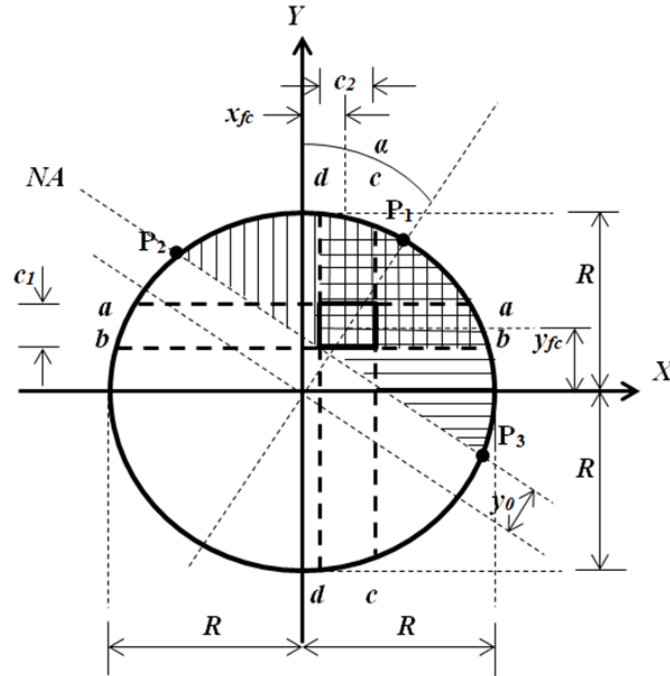


Fig. 4 Moments in the critical sections for a circular isolated footing with eccentric column

where: σ_z is the factored soil pressure anywhere on the base (kN/m^2), σ_{umax} is the factored maximum pressure (kN/m^2), x and y are the coordinates in the X and Y directions of the base (m), y_0 is the distance from the center of the footing to the neutral axis measured on the axis where the resultant moment appears (m), α is the inclination angle of the resultant moment with respect to the Y axis (rad).

2.2.1 Factored moments

Fig. 4 shows the critical sections for the moments. The points P_2 and P_3 have zero pressure, i.e., the straight line joining the points P_2 and P_3 is called the neutral axis and the point P_1 has the maximum pressure.

The moments are obtained in the critical sections that appear on the a , b , c and d axes.

M_{au} on the a axis is estimated through the pressure volume formed by σ_z , the surface delimited by the a axis, the neutral axis and the circumference, this is with respect to the a axis

$$\begin{aligned}
 M_{au} = & - \int_{y_0 \cos \alpha + \sqrt{R^2 - y_0^2} \sin \alpha}^R \int_{-\sqrt{R^2 - y^2}}^{\sqrt{R^2 - y^2}} \sigma_z \left(y - y_{fc} - \frac{c_1}{2} \right) dx dy \\
 & - \int_{y_{fc} + \frac{c_1}{2}}^{y_0 \cos \alpha + \sqrt{R^2 - y_0^2} \sin \alpha} \int_{\frac{y_0 - y \cos \alpha}{\sin \alpha}}^{\sqrt{R^2 - y^2}} \sigma_z \left(y - y_{fc} - \frac{c_1}{2} \right) dx dy
 \end{aligned} \tag{12}$$

M_{bu} on the b axis is obtained through P_u multiplied by $c_1/2$ plus M_{xu} minus the pressure volume formed by σ_z , the surface delimited by the b axis, the neutral axis and the circumference, this pressure is with respect to the b axis

$$\begin{aligned}
M_{bu} = & \frac{P_u c_1}{2} + M_{xu} - \int_{y_0 \cos \alpha + \sqrt{R^2 - y_0^2} \sin \alpha}^R \int_{-\sqrt{R^2 - y^2}}^{\sqrt{R^2 - y^2}} \sigma_z \left(y - y_{fc} + \frac{c_1}{2} \right) dx dy \\
& - \int_{y_{fc} - \frac{c_1}{2}}^{y_0 \cos \alpha + \sqrt{R^2 - y_0^2} \sin \alpha} \int_{\frac{y_0 - y \cos \alpha}{\sin \alpha}}^{\sqrt{R^2 - y^2}} \sigma_z \left(y - y_{fc} + \frac{c_1}{2} \right) dx dy
\end{aligned} \quad (13)$$

M_{cu} on the c axis is estimated through the pressure volume formed by σ_z , the surface delimited by the c axis, the neutral axis and the circumference, this pressure is with respect to the c axis

$$\begin{aligned}
M_{cu} = & - \int_{y_0 \sin \alpha + \sqrt{R^2 - y_0^2} \cos \alpha}^R \int_{-\sqrt{R^2 - x^2}}^{\sqrt{R^2 - x^2}} \sigma_z \left(x - x_{fc} - \frac{c_2}{2} \right) dy dx \\
& - \int_{x_{fc} + \frac{c_2}{2}}^{y_0 \sin \alpha + \sqrt{R^2 - y_0^2} \cos \alpha} \int_{\frac{y_0 - x \sin \alpha}{\cos \alpha}}^{\sqrt{R^2 - x^2}} \sigma_z \left(x - x_{fc} - \frac{c_2}{2} \right) dy dx
\end{aligned} \quad (14)$$

M_{du} on the d axis is obtained through P_u multiplied by $c_2/2$ plus M_{yu} minus the pressure volume formed by σ_z , the surface delimited by the d axis, the neutral axis and the circumference, this pressure is with respect to the d axis

$$\begin{aligned}
M_{du} = & \frac{P_u c_2}{2} + M_{yu} - \int_{y_0 \sin \alpha + \sqrt{R^2 - y_0^2} \cos \alpha}^R \int_{-\sqrt{R^2 - x^2}}^{\sqrt{R^2 - x^2}} \sigma_z \left(x - x_{fc} + \frac{c_2}{2} \right) dy dx \\
& - \int_{x_{fc} - \frac{c_2}{2}}^{y_0 \sin \alpha + \sqrt{R^2 - y_0^2} \cos \alpha} \int_{\frac{y_0 - x \sin \alpha}{\cos \alpha}}^{\sqrt{R^2 - x^2}} \sigma_z \left(x - x_{fc} + \frac{c_2}{2} \right) dy dx
\end{aligned} \quad (15)$$

2.2.2 Factored bending shears

Fig. 5 presents the critical sections for the bending shears. The bending shears are obtained in the critical sections that appear on the e, f, g and h axes.

V_{eu} on the e axis is estimated through the pressure volume formed by σ_z , the surface delimited by the e axis, the neutral axis and the circumference

$$V_{eu} = - \int_{y_0 \cos \alpha + \sqrt{R^2 - y_0^2} \sin \alpha}^R \int_{-\sqrt{R^2 - y^2}}^{\sqrt{R^2 - y^2}} \sigma_z dx dy - \int_{y_{fc} + \frac{c_1}{2} + d}^{y_0 \cos \alpha + \sqrt{R^2 - y_0^2} \sin \alpha} \int_{\frac{y_0 - y \cos \alpha}{\sin \alpha}}^{\sqrt{R^2 - y^2}} \sigma_z dx dy \quad (16)$$

V_{fu} on the f axis is estimated through P_u minus the pressure volume formed by σ_z , the surface delimited by the f axis, neutral axis and the circumference

$$\begin{aligned}
V_{fu} = & P_u - \int_{y_0 \cos \alpha + \sqrt{R^2 - y_0^2} \sin \alpha}^R \int_{-\sqrt{R^2 - y^2}}^{\sqrt{R^2 - y^2}} \sigma_z dx dy \\
& - \int_{y_{fc} - \frac{c_1}{2} - d}^{y_0 \cos \alpha + \sqrt{R^2 - y_0^2} \sin \alpha} \int_{\frac{y_0 - y \cos \alpha}{\sin \alpha}}^{\sqrt{R^2 - y^2}} \sigma_z dx dy
\end{aligned} \quad (17)$$

V_{gu} on the g axis is estimated through the pressure volume formed by σ_z , the surface delimited by the g axis, the neutral axis and the circumference

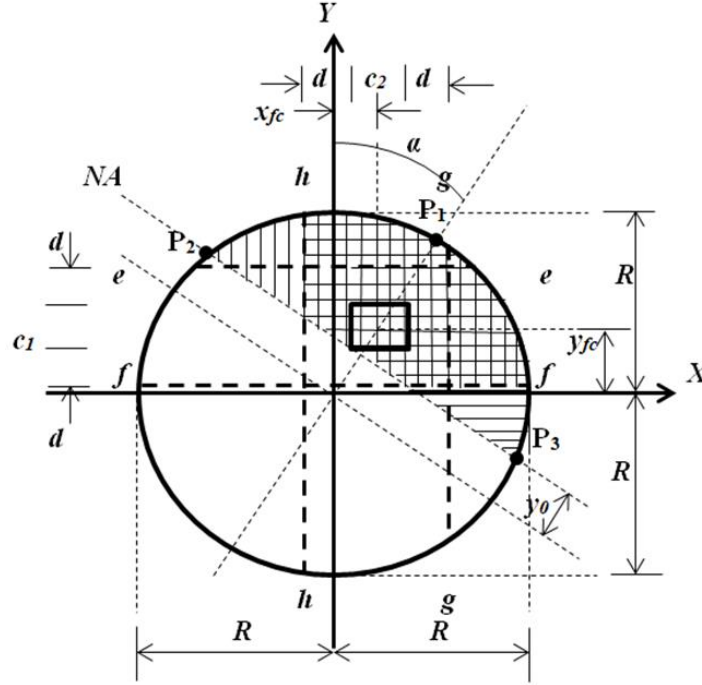


Fig. 5 Bending shears in the critical sections for a circular isolated footing with eccentric column

$$V_{gu} = - \int_{y_0 \sin \alpha + \sqrt{R^2 - y_0^2} \cos \alpha}^R \int_{-\sqrt{R^2 - x^2}}^{\sqrt{R^2 - x^2}} \sigma_z dy dx - \int_{x_{fc} + \frac{c_2}{2} + d}^R \int_{\frac{y_0 - x \sin \alpha}{\cos \alpha}}^{\sqrt{R^2 - x^2}} \sigma_z dy dx \quad (18)$$

V_{hu} on the h axis is estimated through P_u minus the pressure volume formed by σ_z , the surface delimited by the h axis, the neutral axis and the circumference

$$V_{hu} = P_u - \int_{y_0 \sin \alpha + \sqrt{R^2 - y_0^2} \cos \alpha}^R \int_{-\sqrt{R^2 - x^2}}^{\sqrt{R^2 - x^2}} \sigma_z dy dx - \int_{x_{fc} - \frac{c_2}{2} - d}^R \int_{\frac{y_0 - x \sin \alpha}{\cos \alpha}}^{\sqrt{R^2 - x^2}} \sigma_z dy dx \quad (19)$$

2.2.3 Factored punching shear

Fig. 6 presents the critical perimeter for the punching shear. The punching shear is obtained in the critical perimeter that appears on the Y direction from y_2 to y_1 and in the X direction from x_2 to x_1 .

V_{pu} is estimated through P_u minus the pressure volume formed by σ_z , the surface delimited on the Y direction from $y_{fc} - c_1/2 - d/2$ to $y_{fc} + c_1/2 + d/2$ and in the X direction from $x_{fc} - c_2/2 - d/2$ to $x_{fc} + c_2/2 + d/2$

$$V_{pu} = P_u - \int_{y_2}^{y_1} \int_{x_2}^{x_1} \sigma_z dx dy \quad (20)$$

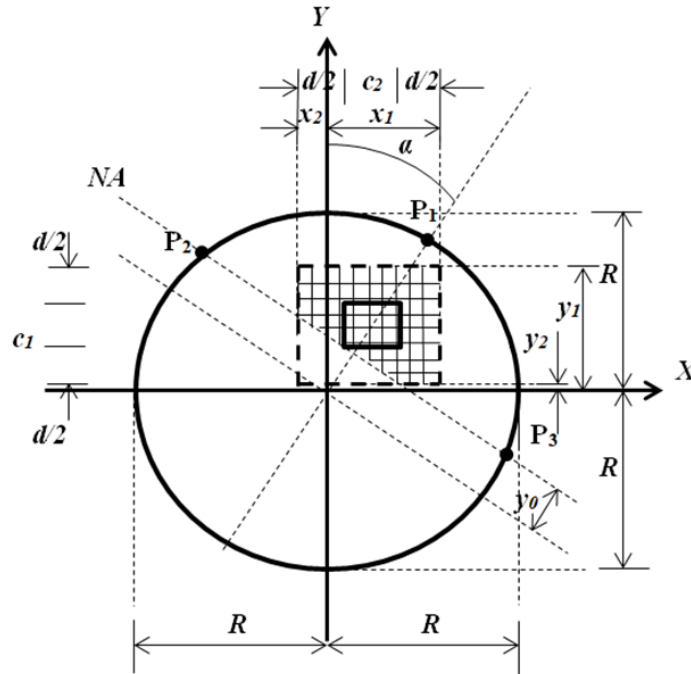


Fig. 6 Punching shear in the critical perimeter for a circular isolated footing with eccentric column

where: $y_2=y_{fc}-c_1/2-d/2$, $y_1=y_{fc}+c_1/2+d/2$, $x_2=x_{fc}-c_2/2-d/2$, $x_1=x_{fc}+c_2/2+d/2$ (When the critical perimeter is located inside the footing), When the critical perimeter is located in a portion outside the footing, the perimeter that is located inside the footing must be considered. Also, if the neutral axis crosses part of the critical perimeter, only the shaded part must be considered as seen in Fig. 6.

2.2.4 Objective function

The minimum cost is

$$C_{min} = V_c C_c + V_s \gamma_s C_s \tag{21}$$

where: C_{min} =minimum cost, C_c =cost of concrete, V_c =volume of concrete, C_s =cost of steel, V_s =volume of steel, γ_s =density of steel=78 kN/m³.

The construction of the steel reinforcement of the footing is as follows: A square or rectangular grid (X and Y directions) and a circular perimeter ring at a distance r (concrete cover) from the free end of the footing inwards.

The total length of the steel bars in the X direction is obtained as follows

$$L_x = 2R + 4 \sum_{j=1}^{(n_x-3)/2} \sqrt{R^2 - (j s_x)^2} \tag{22}$$

where s_x is the space between the reinforcing steel bars in the X direction, n_x is the number of rods in the X direction.

The total length of the steel bars in the Y direction is obtained as follows

$$L_y = 2R + 4 \sum_{i=1}^{(n_y-3)/2} \sqrt{R^2 - (is_y)^2} \quad (23)$$

where s_y is the space between the reinforcing steel bars in the Y direction, n_y is the number of rods in the Y direction.

Length of the circumferential steel bar “ L_c ” is as follows

$$L_c = 2\pi(R - r) \quad (24)$$

The total volume of steel is

$$V_s = a_s(L_y + L_x + L_c) \quad (25)$$

where: a_s is the cross-sectional area of the rod used and is assumed to be the same in both directions.

The volume of concrete is

$$V_c = \pi R^2(d + r) - a_s(L_y + L_x + L_c) \quad (26)$$

Substituting the Eqs. (22), (23) and (24) into Eq. (21) is given

$$C_{min} = [\pi R^2(d + r) - a_s(L_y + L_x + L_c)]C_c + [a_s(L_y + L_x + L_c)]\gamma_s C_s \quad (27)$$

Substituting $\alpha = \gamma_s C_s / C_c \rightarrow \gamma_s C_s = \alpha C_c$ into substituting Eq. (27) is given

$$C_{min} = \left[\left(4R + 4 \sum_{j=1}^{(n_x-3)/2} \sqrt{R^2 - (js_x)^2} + 4 \sum_{i=1}^{(n_y-3)/2} \sqrt{R^2 - (is_y)^2} + 2\pi(R - r) \right) (\alpha - 1)a_s + \pi R^2(d + r) \right] C_c \quad (28)$$

2.2.5 Constraint functions

The adjusted equations for the design of circular footings according to the standard code are shown below (ACI 318S-14 2014).

For moments

$$|M_{au}|, |M_{bu}|, |M_{cu}|, |M_{du}| \leq \phi_f f_y d A_s \left(1 - \frac{A_s f_y}{1.7 b_w d f'_c} \right) \quad (29)$$

The reinforcing areas in both directions are obtained as follows

$$A_{sya} = \rho_x b_{wxa} d \quad (30)$$

$$A_{syb} = \rho_x b_{wxb} d \quad (31)$$

$$A_{sxc} = \rho_y b_{wyc} d \quad (32)$$

$$A_{sxd} = \rho_y b_{wyd} d \quad (33)$$

where: b_{wxa} , b_{wxb} , b_{wyc} and b_{wyd} are obtained as follows

$$b_{wxa} = 2\sqrt{R^2 - (y_{fc} + c_1/2)^2} \quad (34)$$

$$b_{wxb} = 2\sqrt{R^2 - (y_{fc} - c_1/2)^2} \quad (35)$$

$$b_{wyc} = 2\sqrt{R^2 - (x_{fc} + c_2/2)^2} \quad (36)$$

$$b_{syd} = 2\sqrt{R^2 - (x_{fc} - c_2/2)^2} \quad (37)$$

where: A_s and b_w for M_{au} are A_{sya} and b_{wxa} , for M_{bu} are A_{syb} and b_{wxb} , for M_{cu} are A_{sxc} and b_{wyc} , for M_{du} are A_{sxd} and b_{wyd} , f_y is the specified yield strength of reinforcement of steel, f'_c is the specified compressive strength of the concrete at 28 days, A_{sx} is the steel area in the X directions, A_{sy} is the steel area in the Y directions, $\phi_f=0.90$ (bending strength reduction factor).

For bending shears

$$|V_{eu}|, |V_{fu}|, |V_{gu}|, |V_{hu}| \leq 0.17\phi_v \sqrt{f'_c} b_{ws} d \quad (38)$$

where: b_{wsxe} , b_{wsxf} , b_{wsyg} and b_{wsyh} are obtained as follows

$$b_{wsxe} = 2\sqrt{R^2 - (y_{fc} + c_1/2 + d)^2} \quad (39)$$

$$b_{wsxf} = 2\sqrt{R^2 - (y_{fc} - c_1/2 - d)^2} \quad (40)$$

$$b_{wsyg} = 2\sqrt{R^2 - (x_{fc} + c_2/2 + d)^2} \quad (41)$$

$$b_{wsyh} = 2\sqrt{R^2 - (x_{fc} - c_2/2 - d)^2} \quad (42)$$

where: b_{ws} for V_{eu} is b_{wsxe} , for V_{fu} is b_{wsxf} , for V_{gu} is b_{wsyg} , for V_{hu} is b_{wsyh} , $\phi_v=0.85$ (shear strength reduction factor).

For punching shear

$$|V_{pu}| \leq \begin{cases} 0.17\phi_v \left(1 + \frac{2}{\beta_c}\right) \sqrt{f'_c} b_0 d \\ 0.083\phi_v \left(\frac{\alpha_s d}{b_0} + 2\right) \sqrt{f'_c} b_0 d \\ 0.33\phi_v \sqrt{f'_c} b_0 d \end{cases} \quad (43)$$

where: β_c =long side of column/short side of column, b_0 is the critical perimeter, $\alpha_s=20$ (corner column), $\alpha_s=30$ (edge column), and $\alpha_s=40$ (interior column).

For percentages of steel

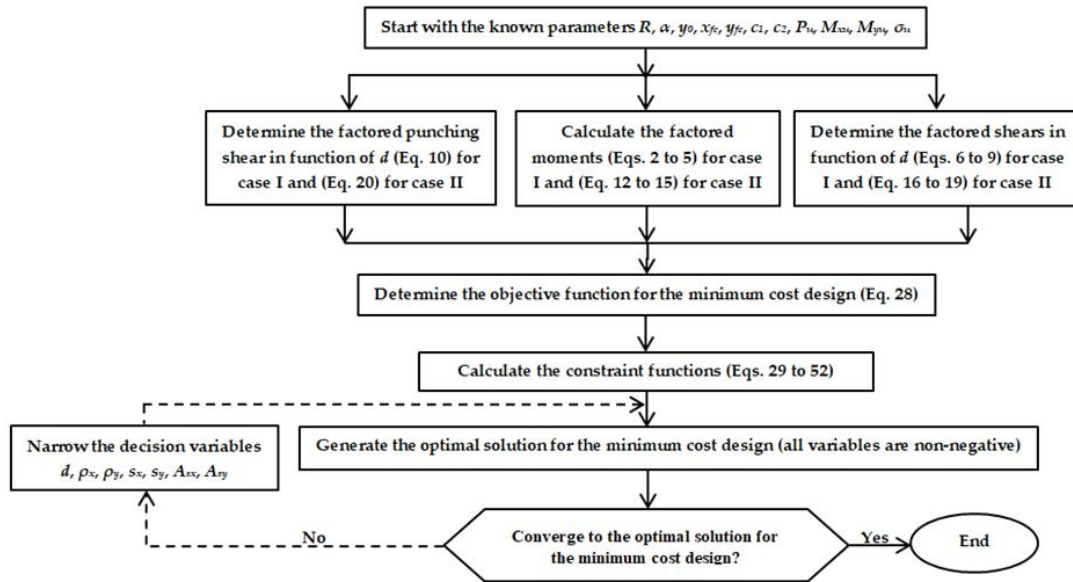


Fig. 7 Flowchart for the minimum cost design of a circular isolated footing with eccentric column

$$\rho_x, \rho_y \leq 0.75 \left[\frac{0.85\beta_1 f'_c}{f_y} \left(\frac{600}{600+f_y} \right) \right] \quad (44)$$

$$\rho_x, \rho_y \geq \begin{cases} \frac{0.25 \sqrt{f'_c}}{f_y} \\ \frac{1.4}{f_y} \end{cases} \quad (45)$$

$$0.65 \leq \beta_1 = \left(1.05 - \frac{f'_c}{140} \right) \leq 0.85 \quad (46)$$

where: β_1 is the factor relating the depth of the equivalent rectangular compressive stress block to the depth of the neutral axis.

For steel areas

$$A_{sy} \geq \begin{cases} A_{sya} = \rho_y b_{wxa} d \\ A_{syb} = \rho_y b_{wxb} d \end{cases} \quad (47)$$

$$A_{sx} \geq \begin{cases} A_{sxc} = \rho_x b_{wyc} d \\ A_{sxd} = \rho_x b_{wyd} d \end{cases} \quad (48)$$

For number of rods

$$n_y = \frac{A_{sy}}{a_s} \quad (49)$$

$$n_x = \frac{A_{sx}}{a_s} \quad (50)$$

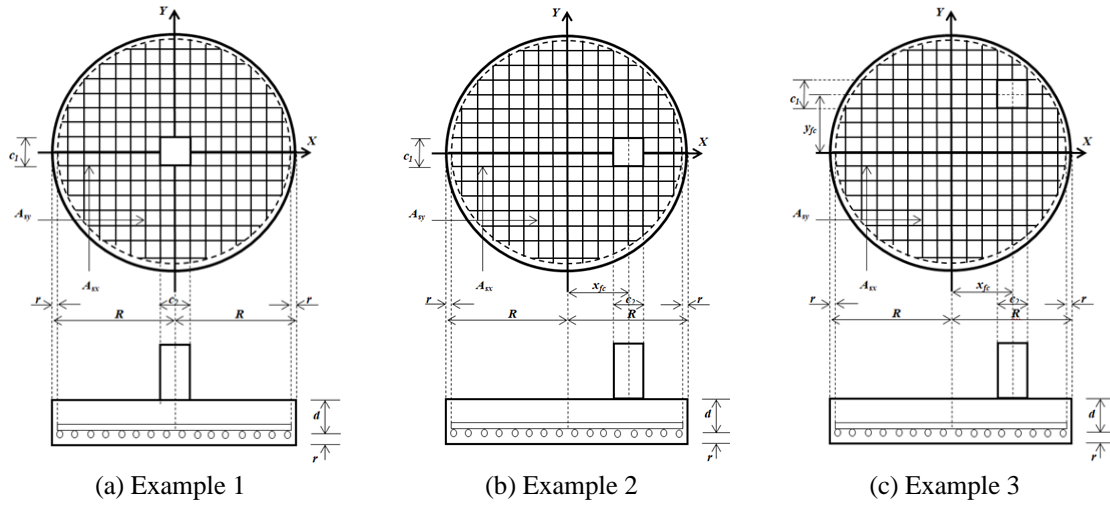


Fig. 8 Three examples for the minimum cost design

Table 1 Example 1: $x_{fc}=0$ and $y_{fc}=0$

Case	Proposed solution			σ_u (kN/m ²)	A_{sx} (cm ²)	A_{sy} (cm ²)	s_x (cm)	s_y (cm)	d (cm)	ρ_x	ρ_y	C_{min} (USD)
	R (m)	y_0 (m)	A_{min} (m ²)									
Example 1.1: $P_D=300$ kN, $P_L=200$ kN, $P_u=680$ kN, $M_{yD}=60$ kN-m, $M_{yL}=40$ kN-m, $M_{yu}=136$ kN-m, $M_{xD}=180$ kN-m, $M_{xL}=120$ kN-m, $M_{xu}=408$ kN-m, $M_{Ru}=430.07$ kN-m, $\alpha=0.3217$ Rad												
1	1.45	-0.58	6.61	309.93	26.28	32.34	13.87	11.27	27.5	0.00333	0.00410	3.53C _c
2	1.55	-0.73	7.55	253.32	28.11	33.59	13.87	11.61	27.5	0.00333	0.00398	4.01C _c
3	1.70	-0.97	9.08	193.91	30.95	35.71	13.87	12.02	27.5	0.00333	0.00384	4.26C _c
4	1.95	-1.36	11.95	133.08	35.53	39.54	13.87	12.46	27.5	0.00333	0.00371	6.30C _c
Example 1.2: $P_D=300$ kN, $P_L=200$ kN, $P_u=680$ kN, $M_{yD}=60$ kN-m, $M_{yL}=40$ kN-m, $M_{yu}=136$ kN-m, $M_{xD}=120$ kN-m, $M_{xL}=80$ kN-m, $M_{xu}=272$ kN-m, $M_{Ru}=304.11$ kN-m, $\alpha=0.4636$ Rad												
1	1.30	-0.82	5.31	311.16	23.53	23.53	13.87	13.87	27.5	0.00333	0.00333	2.72C _c
2	1.40	-0.98	6.16	254.56	25.37	25.37	13.87	13.87	27.5	0.00333	0.00333	3.18C _c
3	1.55	-1.22	7.55	194.78	28.11	28.11	13.87	13.87	27.5	0.00333	0.00333	3.89C _c
4	1.80	-1.62	10.18	133.20	32.78	32.78	13.87	13.87	27.5	0.00333	0.00333	5.27C _c
Example 1.3: $P_D=300$ kN, $P_L=200$ kN, $P_u=680$ kN, $M_{yD}=60$ kN-m, $M_{yL}=40$ kN-m, $M_{yu}=136$ kN-m, $M_{xD}=90$ kN-m, $M_{xL}=60$ kN-m, $M_{xu}=204$ kN-m, $M_{Ru}=245.18$ kN-m, $\alpha=0.5880$ Rad												
1	1.20	-0.89	4.52	328.69	21.70	21.70	13.87	13.87	27.5	0.00333	0.00333	2.36C _c
2	1.30	-1.05	5.31	266.22	23.53	23.53	13.87	13.87	27.5	0.00333	0.00333	2.72C _c
3	1.45	-1.30	6.61	200.82	26.28	26.28	13.87	13.87	27.5	0.00333	0.00333	3.38C _c
4	1.75	*	9.62	128.93	31.87	31.87	13.87	13.87	27.5	0.00333	0.00333	5.00C _c

For space between bars

$$s_y = \frac{b_{wx}a_s}{A_{sy}} \tag{51}$$

$$s_x = \frac{b_{wy}a_s}{A_{sx}} \tag{52}$$

Table 2 Example 2: $x_{fc}=1.50$ m and $y_{fc}=0$

Case	Proposed solution			σ_u (kN/m ²)	A_{sx} (cm ²)	A_{sy} (cm ²)	s_x (cm)	s_y (cm)	d (cm)	ρ_x	ρ_y	C_{min} (USD)
	R (m)	y_0 (m)	A_{min} (m ²)									
Example 2.1: $P_D=480$ kN, $P_L=320$ kN, $P_u=1088$ kN, $M_{yD}=-480$ kN-m, $M_{yL}=-320$ kN-m, $M_{yu}=-1088$ kN-m, $M_{xD}=300$ kN-m, $M_{xL}=200$ kN-m, $M_{xu}=680$ kN-m, $M_{Ru}=870.82$ kN-m, $\alpha=0.6747$ Rad												
1	1.80	-0.62	10.18	326.38	70.33	44.74	25.81	28.22	37.5	0.00753	0.00333	7.44C _c
2	1.95	-0.85	11.95	254.54	84.66	53.92	23.23	27.36	32.5	0.00895	0.00428	8.52C _c
3	2.15	-1.15	14.52	190.57	86.30	57.16	25.14	30.33	32.5	0.00776	0.00411	10.49C _c
4	2.45	-1.62	18.86	131.64	89.88	62.14	27.53	33.86	32.5	0.00666	0.00392	12.94C _c
Example 2.2: $P_D=480$ kN, $P_L=320$ kN, $P_u=1088$ kN, $M_{yD}=-420$ kN-m, $M_{yL}=-280$ kN-m, $M_{yu}=-952$ kN-m, $M_{xD}=300$ kN-m, $M_{xL}=200$ kN-m, $M_{xu}=680$ kN-m, $M_{Ru}=961.67$ kN-m, $\alpha=0.7854$ Rad												
1	1.85	-0.46	10.75	335.89	59.76	45.98	31.22	29.00	37.5	0.00606	0.00333	7.79C _c
2	2.00	-0.68	12.57	258.60	72.27	53.93	27.92	28.58	32.5	0.00731	0.00417	8.55C _c
3	2.20	-0.99	15.21	191.33	74.64	56.97	29.75	31.59	32.5	0.00647	0.00400	10.30C _c
4	2.50	-1.47	19.63	130.29	78.86	61.39	32.02	41.13	32.5	0.00487	0.00379	12.92C _c
Example 2.3: $P_D=480$ kN, $P_L=320$ kN, $P_u=1088$ kN, $M_{yD}=-360$ kN-m, $M_{yL}=-240$ kN-m, $M_{yu}=-816$ kN-m, $M_{xD}=300$ kN-m, $M_{xL}=200$ kN-m, $M_{xu}=680$ kN-m, $M_{Ru}=1062.19$ kN-m, $\alpha=0.8761$ Rad												
1	1.95	-0.30	11.95	325.79	59.62	52.61	33.00	28.04	32.5	0.00630	0.00417	7.90C _c
2	2.05	-0.48	13.20	268.83	60.88	53.91	33.98	29.81	32.5	0.00591	0.00407	8.57C _c
3	2.25	-0.82	15.90	194.05	63.71	56.77	35.65	32.78	32.5	0.00534	0.00390	10.33C _c
4	2.55	-1.29	20.43	135.38	68.99	63.06	37.33	35.30	32.5	0.00484	0.00382	13.03C _c

The flowchart to obtain the minimum cost design of a circular isolated footing with eccentric column for the two cases is shown in Fig. 7.

3. Numerical examples

Tables 1, 2 and 3 show the minimum cost design of a circular isolated footing under biaxial bending based on the same three examples presented in the minimum area paper that appear in Tables 2, 3 and 4 of Luévanos-Soto *et al.* (2024).

Fig. 8 shows the three examples for the minimum cost design of a circular isolated footing.

Fig. 8(a) shows the example 1 ($x_{fc}=0$ and $y_{fc}=0$). Fig. 8(b) presents the example 2 ($x_{fc}=1.50$ m and $y_{fc}=0$). Fig. 8(c) shows the example 3 ($x_{fc}=1.50$ m and $y_{fc}=1.50$ m).

The general data for design of the three examples are $c_1=c_2=0.40$ m, $r=7.5$ cm, $a_s=1.27$ cm² ($1\emptyset 1/2''$), $f'_c=21$ MPa, $f_y=420$ MPa and $\alpha=90$.

Table 1 shows the example 1 for a column located in $x_{fc}=0$ and $y_{fc}=0$ (center of the base).

Table 2 presents the example 2 for a column located in $x_{fc}=1.50$ m and $y_{fc}=0$.

Table 3 shows the example 3 for a column located in $x_{fc}=1.50$ m and $y_{fc}=1.50$ m.

4. Results

This model can be checked as follows.

Table 3 Example 3: $x_{fc}=1.50$ m and $y_{fc}=1.50$ m

Case	Proposed solution			σ_u (kN/m ²)	A_{sx} (cm ²)	A_{sy} (cm ²)	s_x (cm)	s_y (cm)	d (cm)	ρ_x	ρ_y	C_{min} (USD)
	R (m)	y_0 (m)	A_{min} (m ²)									
Example 3.1: $P_D=480$ kN, $P_L=320$ kN, $P_u=1088$ kN, $M_{yD}=-480$ kN-m, $M_{yL}=-320$ kN-m, $M_{yu}=-1088$ kN-m, $M_{xD}=300$ kN-m, $M_{xL}=200$ kN-m, $M_{xu}=680$ kN-m, $M_{Ru}=2375.14$ kN-m, $\alpha=0.2311$ Rad												
1	3.05	1.06	29.22	311.80	91.04	59.75	30.74	46.84	32.5	0.00507	0.00333	18.49C _c
2	3.15	0.87	31.17	255.25	94.01	62.13	30.96	46.84	32.5	0.00504	0.00333	19.53C _c
3	3.30	0.63	34.21	199.41	97.66	65.70	31.51	46.84	32.5	0.00495	0.00333	21.52C _c
4	3.60	0.16	40.72	134.07	104.55	72.63	32.54	46.84	32.5	0.00479	0.00333	25.44C _c
Example 3.2: $P_D=480$ kN, $P_L=320$ kN, $P_u=1088$ kN, $M_{yD}=-420$ kN-m, $M_{yL}=-280$ kN-m, $M_{yu}=-952$ kN-m, $M_{xD}=300$ kN-m, $M_{xL}=200$ kN-m, $M_{xu}=680$ kN-m, $M_{Ru}=2409.93$ kN-m, $\alpha=0.2861$ Rad												
1	3.10	1.14	30.19	309.70	81.68	60.94	34.95	46.84	32.5	0.00446	0.00333	18.52C _c
2	3.20	0.91	32.17	249.49	85.17	63.32	34.82	46.84	32.5	0.00448	0.00333	19.56C _c
3	3.35	0.65	35.26	194.11	89.20	66.78	35.07	46.84	32.5	0.00445	0.00333	22.01C _c
4	3.65	0.17	41.85	130.76	96.47	73.82	35.84	46.84	32.5	0.00435	0.00333	25.91C _c
Example 3.3: $P_D=480$ kN, $P_L=320$ kN, $P_u=1088$ kN, $M_{yD}=-360$ kN-m, $M_{yL}=-240$ kN-m, $M_{yu}=-816$ kN-m, $M_{xD}=300$ kN-m, $M_{xL}=200$ kN-m, $M_{xu}=680$ kN-m, $M_{Ru}=2451.77$ kN-m, $\alpha=0.3393$ Rad												
1	3.20	1.13	32.17	280.47	74.21	63.32	39.97	46.84	32.5	0.00390	0.00333	19.06C _c
2	3.25	1.00	33.18	249.48	76.08	64.51	39.72	46.84	32.5	0.00393	0.00333	19.98C _c
3	3.40	0.69	36.32	191.33	80.83	67.97	39.39	46.84	32.5	0.00396	0.00333	22.06C _c
4	3.70	0.20	43.01	128.49	88.37	75.01	39.76	46.84	32.5	0.00392	0.00333	25.98C _c

For moments on the X axis:

1.- Replacing $y_{fc} + c_1/2$ by $y_0 \cos \alpha - \sqrt{R^2 - y_0^2} \sin \alpha$ on the lower limit and $y - y_{fc} - c_1/2$ by y into Eq. (12) gives: $M_{au}=0$ (moment at the upper end according to Fig. 5).

2.- Replacing $y_{fc} + c_1/2$ by y_{fc} on the lower limit and $y - y_{fc} - c_1/2$ by $y - y_{fc}$ into Eq. (12) gives: M_{au} (moment in the center of the column), and replacing $y_{fc} - c_1/2$ by y_{fc} on the lower limit and $y - y_{fc} + c_1/2$ by $y - y_{fc}$ into Eq. (13) gives: M_{bu} (moment in the center of the column). Now, making $M_{au}=M_{bu}$ and removing $P_u c_1/2$ gives: M_{xu} (moment acting at the center of the column).

For moments on the Y axis:

1.- Replacing $x_{fc} + c_2/2$ by $y_0 \sin \alpha - \sqrt{R^2 - y_0^2} \cos \alpha$ on the lower limit and $x - x_{fc} - c_2/2$ by x into Eq. (14) gives: $M_{cu}=0$ (moment at the far right according to Fig. 5).

2.- Replacing $x_{fc} + c_2/2$ by x_{fc} on the lower limit and $x - x_{fc} - c_2/2$ by $x - x_{fc}$ into Eq. (14) gives: M_{cu} (moment in the center of the column), and replacing $x_{fc} - c_2/2$ by x_{fc} on the lower limit and $x - x_{fc} + c_2/2$ by $x - x_{fc}$ into Eq. (15) gives: M_{du} (moment in the center of the column). Now, making $M_{cu}=M_{du}$ and removing $P_u c_2/2$ gives: M_{yu} (moment acting at the center of the column).

For bending shears on the X axis:

1.- Replacing $y_{fc} + c_1/2 + d$ by $y_0 \cos \alpha - \sqrt{R^2 - y_0^2} \sin \alpha$ in the lower limit of the second member and replacing $y_0 \cos \alpha - \sqrt{R^2 - y_0^2} \sin \alpha$ by R in the lower limit of the first member into Eq. (16) gives: $V_{eu}=0$ (bending shear at the upper end according to Fig. 6).

2.- Replacing $y_{fc} + c_1/2 + d$ by y_{fc} on the lower limit into Eq. (16) gives: V_{eu} (bending shear

in the center of the column), and replacing $y_{fc} - c_1/2 - d$ by y_{fc} on the lower limit into Eq. (17) gives: V_{fu} (bending shear in the center of the column). Now, making $V_{eu}=V_{fu}$ gives: P_u (bending shear acting at the center of the column).

For bending shears in the Y axis:

1.- Replacing $x_{fc} + c_2/2 + d$ by $y_0 \sin \alpha - \sqrt{R^2 - y_0^2} \cos \alpha$ in the lower limit of the second member and replacing $y_0 \sin \alpha - \sqrt{R^2 - y_0^2} \cos \alpha$ by R in the lower limit of the first member into Eq. (18) gives: $V_{gu}=0$ (bending shear at the far right according to Fig. 6).

2.- Replacing $x_{fc} + c_2/2 + d$ by x_{fc} on the lower limit into Eq. (18) gives: V_{gu} (bending shear in the center of the column), and replacing $x_{fc} - c_2/2 - d$ by x_{fc} on the lower limit into Eq. (19) gives: V_{hu} (bending shear in the center of the column). Now, making $V_{gu}=V_{hu}$ gives: P_u (bending shear acting at the center of the column).

Table 1 presents the following for Example 1 ($x_{fc}=0$ and $y_{fc}=0$): When σ_u decreases, R , y_0 (absolute value) except in example 1.3.4 where the area works completely in compression, A_{min} , A_{sx} , A_{sy} and C_{min} increase, s_x , s_y (except in example 1 where it tends to increase), d , ρ_x and ρ_y (except in example 1 where it tends to decrease) are same.

Table 2 presents the following for Example 2 ($x_{fc}=1.50$ and $y_{fc}=0$): When σ_u decreases, R , y_0 (absolute value), A_{min} , A_{sx} , A_{sy} and C_{min} increase, s_x and s_y decrease until example 2.1.2 for example 1 and subsequently increase, for example 2 they decrease until example 2.2.2 and subsequently increase, and for example 3 they increase, ρ_x and ρ_y increase until example 2.1.2 for example 1 and subsequently decrease, for example 2 they increase until example 2.2.2 and subsequently decrease, and for example 3 they decrease, d is the same for all examples (except in examples 2.1.1 and 2.2.1 where is greater).

Table 3 shows the following for Example 3 ($x_{fc}=1.50$ and $y_{fc}=1.50$): When σ_u decreases, R , A_{min} , A_{sx} , A_{sy} and C_{min} increase, y_0 decreases, ρ_x decreases for example 1, for example 2 they increase until example 3.2.2 and subsequently decrease, and for example 3 they increase until example 3.3.3 and subsequently decrease, d , s_y and ρ_y are same.

Also, a comparison is made between the MPLR (model proposed by Luévanos-Rojas et al. 2024b) against the NM (new model) proposed in this paper.

Tables 4 and 5 presents the results of Example 1 of the MPLR against the NM for $P_D=800$ kN and $P_L=700$ kN (Example 1A), $P_D=700$ kN and $P_L=600$ kN (Example 1B), $P_D=600$ kN and $P_L=500$ kN (Example 1C), $P_D=500$ kN and $P_L=400$ kN (Example 1D), $M_{xD}=300$ kN-m, $M_{xL}=200$ kN-m, $M_{yD}=200$ kN-m, $M_{yL}=100$ kN-m, $x_{fc}=0$ m, $y_{fc}=0$ m, $c_1=c_2=0.50$ m, $r=0.075$ m, $a_s=5.07$ cm² (1Ø1"), $\sigma_{max}=200$ kN/m², $f'_c=21$ MPa, $f_y=420$ MPa and $\alpha=90$. Table 4 shows the minimum area and Table 5 presents the minimum cost design.

Tables 6 and 7 show the results of Example 2 of the MPLR against the NM for $P_D=800$ kN and $P_L=600$ kN (Example 2A), $P_D=700$ kN and $P_L=500$ kN (Example 2B), $P_D=600$ kN and $P_L=400$ kN (Example 2C), $P_D=500$ kN and $P_L=300$ kN (Example 2D), $M_{xD}=300$ kN-m, $M_{xL}=200$ kN-m, $M_{yD}=-500$ kN-m, $M_{yL}=-500$ kN-m, $x_{fc}=R/2$ m, $y_{fc}=0$ m, $c_1=c_2=0.50$ m, $r=0.075$ m, $a_s=5.07$ cm² (1Ø1"), $\sigma_{max}=200$ kN/m², $f'_c=21$ MPa, $f_y=420$ MPa and $\alpha=90$. Table 6 shows the minimum area and Table 7 presents the minimum cost design.

Table 4 of the example 1 ($x_{fc}=0$ and $y_{fc}=0$) for minimum area of the MPLR show the following: the smallest values for R and A_{min} are presented in the MPLR because the NM does not present a solution for the two first examples, and for the last two examples the NM governs.

Table 5 of the example 1 ($x_{fc}=0$ and $y_{fc}=0$) for minimum cost design of the MPLR show the following: the smallest values for A_{sx} , A_{sy} , d and C_{min} are presented in the MPLR because the NM

Table 4 Minimum area of Example 1 of the MPLR against the NM: $x_{fc}=0$ and $y_{fc}=0$

Model	Solution				Proposed solution				Pressure acting on the footing		A_{min} (m ²)
	R (m)	y_0 (m)	α (Rad)	M_R (kN-m)	R (m)	y_0 (m)	α (Rad)	M_R (kN-m)	σ_{maxpaf} (kN/m ²)	σ_{minpaf} (kN/m ²)	
Example 1A: $P_D=800$ kN, $P_L=700$ kN, $P=1500$ kN, $M_{yD}=200$ kN-m, $M_{yL}=100$ kN-m, $M_y=300$ kN-m, $M_{xD}=300$ kN-m, $M_{xL}=200$ kN-m, $M_x=500$ kN-m											
NM	No solution										
LR	2.05	-	0.5404	583.10	2.05	-	0.5404	583.10	199.79	27.44	13.20
Example 1B: $P_D=700$ kN, $P_L=600$ kN, $P=1300$ kN, $M_{yD}=200$ kN-m, $M_{yL}=100$ kN-m, $M_y=300$ kN-m, $M_{xD}=300$ kN-m, $M_{xL}=200$ kN-m, $M_x=500$ kN-m											
NM	No solution										
LR	1.98	-	0.5404	583.10	2.00	-	0.5404	583.10	196.25	10.65	12.57
Example 1C: $P_D=600$ kN, $P_L=500$ kN, $P=1100$ kN, $M_{yD}=200$ kN-m, $M_{yL}=100$ kN-m, $M_y=300$ kN-m, $M_{xD}=300$ kN-m, $M_{xL}=200$ kN-m, $M_x=500$ kN-m											
NM	1.91	-1.55	0.5404	583.10	1.95	-1.61	0.5404	583.10	190.73	0	11.95
LR	2.12	-	0.5404	583.10	2.125	-	0.5404	583.10	154.91	0.17	14.19
Example 1D: $P_D=500$ kN, $P_L=400$ kN, $P=900$ kN, $M_{yD}=200$ kN-m, $M_{yL}=100$ kN-m, $M_y=300$ kN-m, $M_{xD}=300$ kN-m, $M_{xL}=200$ kN-m, $M_x=500$ kN-m											
NM	1.87	-1.15	0.5404	583.10	1.95	1.61	0.5404	583.10	190.73	0	11.95
LR	2.59	-	0.5404	583.10	2.60	-	0.5404	583.10	84.62	0.14	21.24

where: σ_{maxpaf} is the maximum pressure acting on the footing, σ_{minpaf} is the minimum pressure acting on the footing.

Table 5 Minimum cost design of Example 1 of the MPLR against the NM: $x_{fc}=0$ and $y_{fc}=0$

Model	Proposed solution					A_{sx} (cm ²)	A_{sy} (cm ²)	s_x (cm)	s_y (cm)	d (cm)	ρ_x	ρ_y	C_{min} (USD)
	R (m)	y_0 (m)	α (Rad)	M_{Ru} (kN-m)	σ_u (kN/m ²)								
Example 1A: $P_D=800$ kN, $P_L=700$ kN, $P_u=2080$ kN, $M_{yD}=200$ kN-m, $M_{yL}=100$ kN-m, $M_{yu}=400$ kN-m, $M_{xD}=300$ kN-m, $M_{xL}=300$ kN-m, $M_{xu}=680$ kN-m													
NM	No solution												
LR	2.05	-	0.5317	788.92	274.14	64.39	64.39	32.05	32.05	47.50	0.00333	0.00333	10.85C _c
Example 1B: $P_D=700$ kN, $P_L=600$ kN, $P_u=1800$ kN, $M_{yD}=200$ kN-m, $M_{yL}=100$ kN-m, $M_{yu}=400$ kN-m, $M_{xD}=300$ kN-m, $M_{xL}=200$ kN-m, $M_{xu}=680$ kN-m													
NM	No solution												
LR	2.00	-	0.5317	788.92	268.80	56.19	63.55	35.82	31.67	42.50	0.00333	0.00377	9.73C _c
Example 1C: $P_D=600$ kN, $P_L=500$ kN, $P_u=1520$ kN, $M_{yD}=200$ kN-m, $M_{yL}=100$ kN-m, $M_{yu}=400$ kN-m, $M_{xD}=300$ kN-m, $M_{xL}=200$ kN-m, $M_{xu}=680$ kN-m													
NM	1.95	-1.65	0.5317	788.92	260.42	48.38	52.24	40.56	37.56	37.50	0.00333	0.00360	8.15C _c
LR	2.125	-	0.5317	788.92	211.83	59.72	63.89	35.82	33.49	42.50	0.00333	0.00356	10.79C _c
Example 1D: $P_D=500$ kN, $P_L=400$ kN, $P_u=1240$ kN, $M_{yD}=200$ kN-m, $M_{yL}=100$ kN-m, $M_{yu}=400$ kN-m, $M_{xD}=300$ kN-m, $M_{xL}=200$ kN-m, $M_{xu}=680$ kN-m													
NM	1.95	-1.31	0.5317	788.92	241.53	43.62	54.17	44.98	36.22	32.50	0.00347	0.00431	7.28C _c
LR	2.60	-	0.5317	788.92	115.54	64.74	64.69	40.57	40.60	37.50	0.00333	0.00333	14.12C _c

Table 6 Minimum area of Example 2 of the MPLR against the NM: $x_{fc}=R/2$ and $y_{fc}=0$

Model	Solution				Proposed solution				Pressure acting on the footing		A_{min} (m ²)
	R (m)	y_0 (m)	α (Rad)	M_R (kN-m)	R (m)	y_0 (m)	α (Rad)	M_R (kN-m)	σ_{maxpaf} (kN/m ²)	σ_{minpaf} (kN/m ²)	
Example 2A: $P_D=800$ kN, $P_L=600$ kN, $P=1400$ kN, $M_{yD}=-500$ kN-m, $M_{yL}=-500$ kN-m, $M_y=-1000$ kN-m, $M_{xD}=300$ kN-m, $M_{xL}=200$ kN-m, $M_x=500$ kN-m											
NM	No solution										
LR	2.07	-	-	672.01	2.10	-	-	686.22	195.40	6.71	13.85
Example 2B: $P_D=700$ kN, $P_L=500$ kN, $P=1200$ kN, $M_{yD}=-500$ kN-m, $M_{yL}=-500$ kN-m, $M_y=-1000$ kN-m, $M_{xD}=300$ kN-m, $M_{xL}=200$ kN-m, $M_x=500$ kN-m											
NM	1.92	-1.88	0.2994	522.59	1.95	-1.91	0.3277	528.11	194.03	0	11.95
LR	1.91	-	-	520.88	2.00	-	-	538.52	181.20	9.79	12.57
Example 2C: $P_D=600$ kN, $P_L=400$ kN, $P=1000$ kN, $M_{yD}=-500$ kN-m, $M_{yL}=-500$ kN-m, $M_y=-1000$ kN-m, $M_{xD}=300$ kN-m, $M_{xL}=200$ kN-m, $M_x=500$ kN-m											
NM	1.84	-1.56	-0.1593	506.36	1.85	-1.58	-0.1489	505.59	196.97	0	10.75
LR	2.00	-	-	500.00	2.00	-	-	500.00	159.15	0	12.57
Example 2D: $P_D=500$ kN, $P_L=300$ kN, $P=800$ kN, $M_{yD}=-500$ kN-m, $M_{yL}=-500$ kN-m, $M_y=-1000$ kN-m, $M_{xD}=300$ kN-m, $M_{xL}=200$ kN-m, $M_x=500$ kN-m											
NM	1.84	-0.96	-0.4862	565.42	1.85	-0.98	-0.4795	563.56	196.13	0	10.75
LR	2.50	-	-	500.00	2.50	-	-	500.00	81.49	0	19.63

does not present a solution for the two first examples, and for the last two examples the NM governs.

Table 6 of the example 2 ($x_{fc}=R/2$ and $y_{fc}=0$) for minimum area of the MPLR show the following: the smallest values for R and A_{min} are presented in the MPLR because the NM does not present a solution for the first example, and for the last three examples the NM governs.

Table 7 of the example 2 ($x_{fc}=R/2$ and $y_{fc}=0$) for minimum cost design of the MPLR show the following: the smallest values for A_{sx} , A_{sy} , d and C_{min} are presented in the MPLR because the NM does not present a solution for the first example, and for the last three examples the NM governs for A_{sx} (except in examples 2B and 2C), A_{sy} , d (except in example 2D) and C_{min} .

Fig. 9 shows the minimum cost of examples 1, 2, 3 for the four cases.

Fig. 9 shows the following for the three examples: The lowest cost appears in case 1 for all examples, because the factored soil pressure acting on the footing is greater. The largest cost appears in case 4 for all examples, because the factored soil pressure acting on the footing is lower.

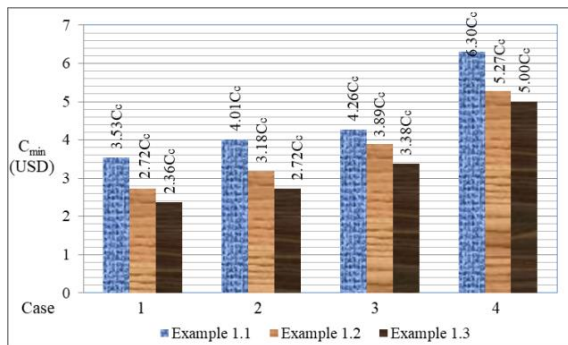
Fig. 10 presents the results of Example 1 of the MPLR against the NM. Fig. 10(a) shows the minimum area and Fig. 10(b) presents the minimum cost.

Fig. 10(a) presents the following results (Example 1): The smaller area appears in the NM compared to the MPLR in Examples 1C and 1D, and the smaller area appears in the MPLR compared to the NM in Examples 1A and 1B since the NM has no solution. The largest difference appears in example 1D of 1.78 times the MPLR than the NM.

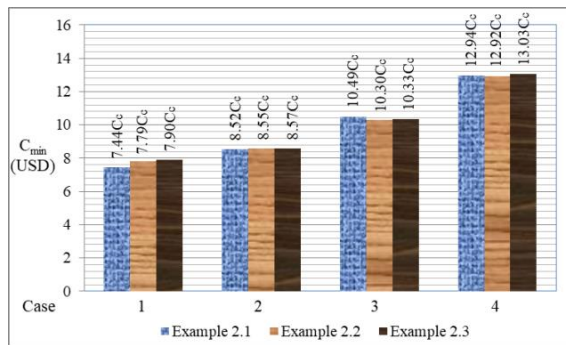
Fig. 10(b) shows the following results (Example 1): The smaller cost appears in the NM compared to the MPLR in Examples 1C and 1D, and the smaller cost appears in the MPLR compared to the NM in Examples 1A and 1B since the NM has no solution. The largest difference appears in example 1D of 1.94 times the MPLR than the NM.

Table 7 Minimum cost design of Example 2 of the MPLR against the NM: $x_{fc}=R/2$ and $y_{fc}=0$

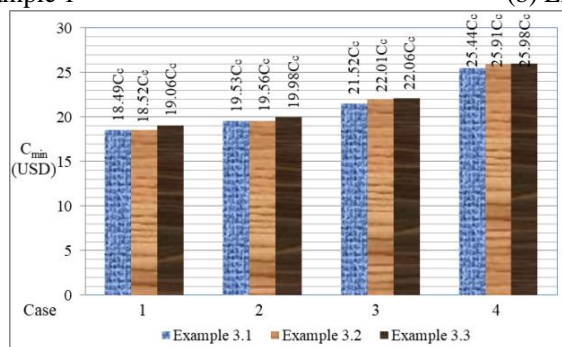
Model	Proposed solution					A_{sx} (cm ²)	A_{sy} (cm ²)	s_x (cm)	s_y (cm)	d (cm)	ρ_x	ρ_y	C_{min} (USD)
	R (m)	y_0 (m)	α (Rad)	M_{Ru} (kN-m)	σ_u (kN/m ²)								
Example 2A: $P_D=800$ kN, $P_L=600$ kN, $P_u=1920$ kN, $M_{yD}=-500$ kN-m, $M_{yL}=-500$ kN-m, $M_{yu}=-1400$ kN-m, $M_{xD}=300$ kN-m, $M_{xL}=200$ kN-m, $M_{xu}=680$ kN-m													
NM	No solution												
LR	2.10	-	0.7361	917.53	264.73	86.79	86.79	24.36	24.36	62.50	0.00333	0.00333	15.12C _c
Example 2B: $P_D=700$ kN, $P_L=500$ kN, $P_u=1640$ kN, $M_{yD}=-500$ kN-m, $M_{yL}=-500$ kN-m, $M_{yu}=-1400$ kN-m, $M_{xD}=300$ kN-m, $M_{xL}=200$ kN-m, $M_{xu}=680$ kN-m													
NM	1.95	-1.94	0.2847	708.52	263.80	73.52	61.22	26.69	32.05	47.50	0.00400	0.00333	10.26C _c
LR	2.00	-	0.3393	721.11	216.64	71.35	69.41	28.21	29.00	52.50	0.00342	0.00333	11.60C _c
Example 2C: $P_D=600$ kN, $P_L=400$ kN, $P_u=1360$ kN, $M_{yD}=-500$ kN-m, $M_{yL}=-500$ kN-m, $M_{yu}=-1400$ kN-m, $M_{xD}=300$ kN-m, $M_{xL}=200$ kN-m, $M_{xu}=680$ kN-m													
NM	1.85	-1.56	-0.2059	694.67	269.17	94.13	45.91	19.77	40.53	37.50	0.00684	0.00333	8.59C _c
LR	2.00	-	-0.0588	681.18	216.64	82.63	56.19	24.36	35.82	42.50	0.00490	0.00333	10.33C _c
Example 2D: $P_D=500$ kN, $P_L=300$ kN, $P_u=1080$ kN, $M_{yD}=-500$ kN-m, $M_{yL}=-500$ kN-m, $M_{yu}=-1400$ kN-m, $M_{xD}=300$ kN-m, $M_{xL}=200$ kN-m, $M_{xu}=680$ kN-m													
NM	1.85	-0.90	-0.5328	789.43	273.27	78.06	58.05	23.84	32.05	47.50	0.00448	0.00333	9.63C _c
LR	2.50	-	-0.0734	681.84	110.56	97.48	62.07	25.85	40.60	37.50	0.00523	0.00333	14.12C _c



(a) Example 1



(b) Example 2



(c) Example 3

Fig. 9 Minimum cost of the three examples for the four cases

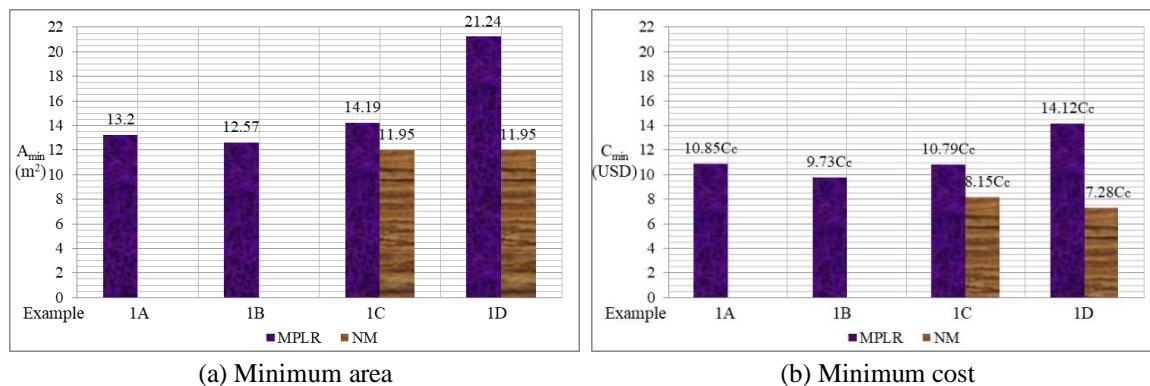


Fig. 10 Comparison of Example 1 of MPLR against the NM

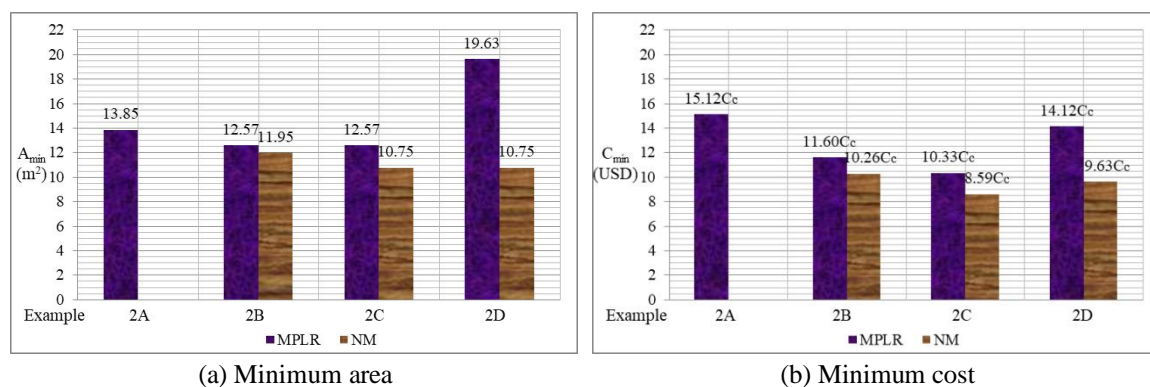


Fig. 11 Comparison of Example 2 of MPLR and NM

Fig. 11 presents the results of Example 2 of the MPLR against the NM. Fig. 11(a) shows the minimum area and Fig. 11(b) presents the minimum cost.

Fig. 11(a) presents the following results (Example 2): The smaller area appears in the NM compared to the MPLR in Examples 1B, 1C and 1D, and the smaller area appears in the MPLR compared to the NM in Example 1A since the NM has no solution. The largest difference appears in example 1D of 1.83 times the MPLR than the NM.

Fig. 11(b) shows the following results (Example 2): The smaller cost appears in the NM compared to the MPLR in Examples 1B, 1C and 1D, and the smaller cost appears in the MPLR compared to the NM in Example 1A since the NM has no solution. The largest difference appears in example 1D of 1.47 times the MPLR than the NM.

5. Conclusions

This paper shows a model to estimate the minimum cost design (thickness and areas of reinforcing steel in both directions) in a circular isolated footing with an eccentric column considering that the area in contact with the ground works partially in compression, that is, a part of the contact surface of the footing works in compression and the other part has zero pressure.

This research shows the minimum cost design for a circular isolated footing under biaxial bending. Assuming that the footing is rigid and supported on elastic soils, the column is eccentrically positioned and the pressure diagram is linear.

The model Luévanos-Rojas *et al.* (2024b) is shown below: the independent variables (known data) are R , c_1 , c_2 , x_{fc} , y_{fc} , P_u , M_{xu} and M_{yu} , and the dependent variables are C_{min} , A_{sx} , A_{sy} , s_x , s_y , d , ρ_x and ρ_y (data to estimate).

The new model is shown as follows: the independent variables (known data) are σ_u , c_1 , c_2 , x_{fc} , y_{fc} , R , c_1 , c_2 , x_{fc} , y_{fc} , α , y_0 , P_u , M_{xu} and M_{yu} , and the dependent variables are C_{min} , A_{sx} , A_{sy} , s_x , s_y , d , ρ_x and ρ_y (data to estimate).

The contributions of this paper are:

1) Some engineers obtain the thickness and areas of reinforcing steel of a circular isolated footing under biaxial bending, but considering a uniform pressure with a concentric column.

2) Another engineering practice to estimate the thickness and areas of reinforcing steel using optimization techniques, but the column is in the center of the base and the contact area of the footing operates completely in compression (Lopez-Chavarria *et al.* 2019).

3) Other engineers determine the thickness and areas of reinforcing steel of a circular isolated footing under biaxial bending with an eccentric column supported on elastic soils, but the area works completely in compression (Luévanos-Rojas *et al.* 2024b).

4) The new model can be adapted to other construction codes, considering the resistant moments, the bending shears that the concrete can resist and the punching shear that the concrete can resist, according to each code.

5) This model presents a great saving for minimum area compared with the model Luévanos-Rojas *et al.* (2024b) of 15.79% in Example 1C and 43.74% in Example 1D (see Table 4), 4.93% in Example 2B, 14.48% in Example 2C and 45.24% in Example 2D (see Table 6).

6) The new model presents a great saving for minimum cost design compared with the model Luévanos-Rojas *et al.* (2024b) of 24.47% in Example 1C and 48.44% in Example 1D (see Table 5), 11.55% in Example 2B, 16.84% in Example 2C and 31.80% in Example 2D (see Table 7).

Suggestions for the following investigations may be:

1.- Minimum surface for a rectangular isolated footing with an eccentric column considering that the area in contact with the ground works partially in compression.

2.- Minimum cost design for a rectangular isolated footing with an eccentric column considering that the area in contact with the ground works partially in compression.

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