

Free vibration analysis of a sandwich cylindrical shell with an FG core based on the CUF

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Abstract. An analytical approach for the free vibration behavior of a sandwich cylindrical shell with a functionally graded (FG) core is presented. It is considered that the FG distribution is in the direction of thickness. The material properties are temperature-dependent. The sandwich cylindrical shell with a FG core is considered with two cases. In the first model, i.e., Ceramic-FGM-Metal (CFM), the interior layer of the cylindrical shell is rich metal while the exterior layer is rich ceramic and the FG material is located between two layers and for the second model i.e., Metal-FGM-Ceramic (MFC), the material distribution is in reverse order. This study develops Carrera's Unified Formulation (CUF) to analyze sandwich cylindrical shell with an FG core for the first time. Considering the Principle of Virtual Displacements (PVDs) according to the CUF, the dependent boundary conditions and governing equations are obtained. The coupled governing equations are derived using Galerkin's method. In order to validate the present results, comparisons are made with the available solutions in the previous researches. The effects of different geometrical and material parameters on the free vibration behavior of a sandwich cylindrical shell with an FG core are examined.

Keywords: Carrera's unified formulation; free vibration analysis; functionally graded material; principle of virtual displacements; sandwich cylindrical shell

1. Introduction

Recently, FG structures reinforced by stiffeners are widely utilized in different industry branches. Also, the application of sandwich structures in various fields of engineering, including aerospace, mechanical, and civil, has been widely developed in recent years. According to their low weight and high performance, the attention of engineers and researchers were attracted to study their structural behavior. This kind of structure exhibits several advantages such as, high strength to low weight ratio, good thermal isolation, improved nonlinear capacity, decent local and global buckling behavior and so on. Moreover, the application of composite materials in many commercial aircraft indicates the importance of studying these types of structures in both aerospace and aeronautical industries (Gohardani *et al.* 2014). FG sandwich has a favorable mechanical property in the special high-temperature environments due to the core fabrication with FG material with a continuous variation of the material properties along a specific direction and the high stiffness to weight ratio of the design of the sandwich structures. Thus, the FG sandwich structures have been widely applied in the actual industrial application as fundamental ones of the system,

such as bridges, architectural structures, hydraulic structures, and so on. Some studies have been focused on the nonlinear analyses of functionally graded (FG) and composite structures. The vibration response of cylindrical panels with the FG material via the theory of higher-order shear deformation shell was examined by Babaei *et al.* (2019). Sofiyev *et al.* (2017) studied the vibration behavior of the composite cylindrical shells resting on the elastic foundation via the shear deformation theory (SDT). Nonlinear vibrations of metal foam cylindrical shells reinforced with graphene platelets and FG sandwich thin nanoshells conveying fluid incorporating surface stress influence were analyzed by Wang *et al.* (2019a, b). The vibration response of a composite cylindrical shell was presented by Zhang *et al.* (2018). Free and forced vibrations of nanocomposite beams reinforced by 3D graphene foam were analyzed by Yang and Wang (2020). Giunta *et al.* (2013) investigated the vibration response of simply supported, cross-ply beams utilizing refined theories. Zhang *et al.* (2014) investigated the thermal buckling analysis of functionally graded plates using a local Kriging meshless method. The nonlinear thermomechanical analysis of moderately thick functionally graded plates using a local Petrov-Galerkin approach with moving Kriging interpolation was studied by Zhu *et al.* (2014). An element-free IMLS-Ritz method for the numerical solution of three-dimensional wave equations and an element-free computational framework for elastodynamic problems based on the IMLS-Ritz method was presented by (Zhang *et al.* 2015a, b). Vibration behaviors of FG porous plates with

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different loads were investigated by Wang (2018), Wang and Zu (2017a, b, c). Also, the Chebyshev collocation technique for vibration analysis of sandwich cylindrical shells with metal foam core and free vibration analysis of metal foam core sandwich beams on elastic foundation using Chebyshev collocation method was examined by Wang *et al.* (2020), Wang and Zhao (2019).

Some research is paid attention to vibration analyses of the stiffened cylindrical shell with the functionally graded material. Duc and Thang (2015) investigated the vibration analysis of the cylindrical shells reinforced by stiffeners with the FGM and initial imperfection resting on the elastic foundation exposed to the damping and mechanical loads. The vibration response of the cylindrical shell reinforced by stiffeners with the FGM embedded within an elastic foundation exposed to the external excitation was examined by Dung and Nam (2014). Foroutan *et al.* (2019b) addressed the vibration of spiral stiffened cylindrical shells embedded within an elastic foundation. Bich *et al.* (2013) presented the static and dynamic responses of stiffened cylindrical shells with functionally graded material. The vibration of spiral stiffened cylindrical shells with FGM embedded within the nonlinear elastic foundation exposed to the axial excitation was examined by Foroutan *et al.* (2018).

In the previous literature, the researchers have not investigated the vibration analyses of carbon nanotube (CNT) cylindrical shell and plate. Some researchers have been focused on the nonlinear behavior of the cylindrical shells and plates stiffened by a CNT.

The buckling and post-buckling analysis of FG-CNT plate with different methods have been investigated by Zhang (2017a), Zhang and Liew (2016a), Zhang *et al.* (2015c, 2016a, b, c). Predicting buckling and vibration behaviors of FG-CNT reinforced composite cylindrical panels with three-dimensional flexibilities were examined by Liew and Alibeigloo (2020). Liew *et al.* (2020) studied the recent progress of FG-CNT reinforced composites and structures. Pan *et al.* (2019) presented the modeling geometrically nonlinear large deformation behaviors of matrix cracked hybrid composite deep shells containing CNTRC layers. Also, nonlinear, free, and forced vibration behaviors of FG-CNT plate under various loads with different methods have been analyzed by Lei *et al.* (2015a), Zhang (2017b, c), Zhang and Liew (2015, 2016b), Zhang *et al.* (2015d, e, f, 2016d, e, f, g, h). Nonlinear analyses of FG-CNT cylindrical panels and shells subjected to the different loads have been studied by Lei *et al.* (2014), Zhang *et al.* (2017, 2016i). Nonlinear vibration of a micro cylindrical shell reinforced by carbon nanotubes (CNTs) with considering agglomeration effects was analyzed by Tohidi *et al.* (2018). Zghal *et al.* (2018) studied the free vibration behavior of FG composite shells reinforced by CNT utilizing the first-order shear deformation theory and Chebyshev-Ritz formulation. Nonlinear and vibration analyses of laminated FG-CNT plate with different methods have been investigated by Zhang and Xiao (2017), Zhang and Selim (2017), Lei *et al.* 2016, 2015b). Nonlinear vibration behavior of piezoelectric plates reinforced with CNT via the differential quadrature method was examined

by Arani *et al.* (2016). Shen and Xiang (2012) reported the vibration of CNTRC skew cylindrical shells with FGM utilizing the formulation of Chebyshev-Ritz. The vibration of cylindrical shells stiffened by a CNT in thermal environments was investigated by Song *et al.* (2016). Foroutan *et al.* (2019a) addressed the vibration of imperfect FG cylindrical panels stiffened by a CNT under a thermal environment subjected to external pressure. The vibration responses of CNTRC cylindrical shells with the FGM under the thermal conditions were presented by Chakraborty *et al.* (2019). The vibration and stability responses of the cylindrical panels with FGM reinforced by a carbon nanotube via the semi-analytical approach investigated by Qin *et al.* (2019). Carrera and Ettore (1995) investigated the vibration of rotating CNTRC cylindrical shells with FGM and arbitrary boundary conditions.

A class of two-dimensional (2D) theories utilizing a compact notation was introduced by Carrera (1997), which in literature; was later named Carrera's Unified Formulation (CUF). The above-mentioned compact notation can be expanded the field of displacement to arbitrary expansion order. For this purpose, a single 3×3 matrix has been used, which is named as fundamental nuclei. These fundamental nuclei can be utilized to show the approaches of the variable description, such as Layer-wise (LW) and Equivalent Single Layer (ESL) models (Carrera 1998a, b, c, 2003, Carrera and Demasi 2002a, b). Carrera *et al.* (2011) has been investigated the theoretical foundations of the unified method. Recently, CUF has also been utilized in the formulation of the shell, plate, and beam theories (Pagani *et al.* 2013, Carrera and Pagani 2014, Carrera 1999, Cinefra *et al.* 2015a, b, c, Neves *et al.* 2012, Mashat *et al.* 2014, Vigiueti *et al.* 2019).

Considering previous works, it is indicated that there is no research on the free vibration of a sandwich cylindrical shell with an FG core according to the CUF. Therefore, the novelties of the present paper may be summarized as follows:

- (i) Development of the Carrera's Unified Formulation (CUF) for the free vibration behavior of a sandwich cylindrical shell with an FG core for the first time. The 3D displacement field $u(x, y, z)$ according to the CUF for the 2D plate theory, can be expanded as a set of thickness functions depending only on the thickness coordinate z and the corresponding variables depending on the in-plane coordinates x and y .
- (ii) A sandwich cylindrical shell with an FG core has three layers, including the ceramic, FGM and metal in two cases, which is examined as a three-dimensional (3D) structure. Also, the material properties are temperature-dependent.
- (iii) Furthermore, the resilience of the thickness, which is neglected in most of the researches on functionally graded structures, as well as continuity of the displacement field and the zig-zag form in layered structures, are investigated in this paper.

To this end, the governing equations based on the CUF

are obtained, and in order to validate the present results, comparisons are made with the available solutions in the previous researches. The effects of different geometrical and material parameters on the vibration of a sandwich cylindrical shell with an FG core are examined.

2. Sandwich cylindrical shell with FG core

The sandwich cylindrical shell with an FG core that the system of coordinate (x, θ, z) is illustrated in Fig. 1, in which the axes of x , θ and z are the axial, circumferential, and radial coordinate variables of the sandwich cylindrical shell with a FG core, respectively. The cylindrical shell has radius R , thickness h , and length L .

The volume fractions regarding the power-law are as (Ahmadi and Foroutan 2020)

$$\begin{aligned} V_c(z) &= \left(\frac{2z+h}{2h}\right)^K \\ V_m(z) &= 1 - V_c(z) \end{aligned} \quad (1)$$

In Eq. (1), $K \geq 0$ is the shell material power-law index. The subscripts m and c are referred to the metal and ceramic, respectively. A material coefficient P is defined as a temperature nonlinear function (Duc and Thang 2015, Foroutan *et al.* 2019a)

$$P = P_0(P_{-1}T^{-1} + 1 + P_1T + P_2T^2 + P_3T^3) \quad (2)$$

In the present study, a sandwich cylindrical shell with an FG core is assumed in two cases which are shown in Fig. 2.

Considering the mentioned law, Young's modulus and mass density are obtained as (Nam *et al.* 2018, Wu and Li 2012, Arefi 2015):

Case I: Metal-FGM-Ceramic

$$[E(z), \rho(z)] = \begin{cases} (E_m, \rho_m) & t_0 \leq z \leq t_1 \\ (E_m, \rho_m) + (E_{cm}, \rho_{cm}) \left(\frac{2z+h_m}{2h_m}\right)^K & t_1 \leq z \leq t_2 \\ (E_c, \rho_c) & t_2 \leq z \leq t_3 \end{cases} \quad (3a)$$

Case II: Ceramic-FGM-Metal

$$[E(z), \rho(z)] = \begin{cases} (E_c, \rho_c) & t_0 \leq z \leq t_1 \\ (E_c, \rho_c) + (E_{mc}, \rho_{mc}) \left(\frac{2z+h_m}{2h_m}\right)^K & t_1 \leq z \leq t_2 \\ (E_m, \rho_m) & t_2 \leq z \leq t_3 \end{cases} \quad (3b)$$

where ρ , and E are the mass density and Young's modulus of the multilayer FG shell, respectively.

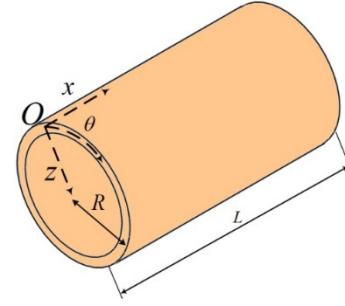
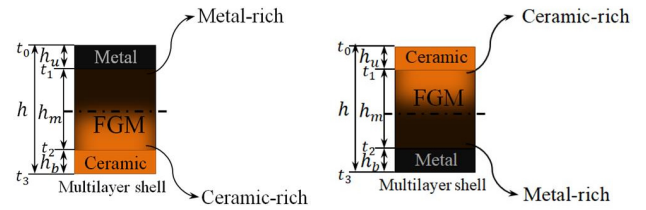


Fig. 1 Configuration of a sandwich cylindrical shell with an FG core



Case I: Metal-FGM-Ceramic

Case II: Ceramic-FGM-Metal

Fig. 2 The material distribution of sandwich cylindrical shell with an FG core

3. Governing equation based on the CUF

3.1 Displacement base field

With regard to the CUF, three components of displacement are represented as a set of functions of thickness for the k th layer in a layered cylindrical shell and the respective displacement, which is related to the in-plane coordinates. According to above-mentioned expiations, displacement $u^k(x, \theta, z) = \{u^k(x, \theta, z), v^k(x, \theta, z), w^k(x, \theta, z)\}^T$ can be written in the following expansion

$$\begin{aligned} u^k(x, \theta, z) &= F_r^k(z)u_r^k(x, \theta) \\ \delta u^k(x, \theta, z) &= F_s^k(z)\delta u_s^k(x, \theta) \end{aligned} \quad (4)$$

In Eq. (4), N is the expansion order utilized for the direction of thickness and $s, \tau = 0, 1, \dots, N$. Also, repetitious indexes are implicitly summed over considering the convention of Einstein summation. As shown in Fig. 3, subscripts $s, \tau = N$, and $s, \tau = 0$ show the values of the bottom and top surface, respectively. Also, other subscripts expressed the surfaces among the bottom and top surfaces.

The models of Equivalent Single Layer (ESL) are created, when one of the heterogeneous laminated structures treats as a statically equivalent single layer having a behavior of the complex constitutive. For $\frac{1}{1-z^2}$, the first few terms of the series of Maclaurin are utilized as functions of thickness to include by the other models of ESL.

$$\begin{aligned} F_0 &= z^0 = 1, \quad F_r = z^r, \quad F_N = z^N \\ r &= 1, \dots, N-1 \end{aligned} \quad (5)$$

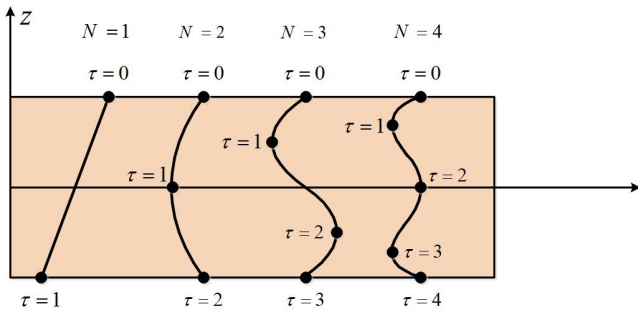


Fig. 3 Linear and higher-order distribution of displacements according to the CUF

and when the expansions for the direction of thickness are assumed separately for each layer of the multilayer, these models are Layer-Wise (LW). Therefore, to guarantee the continuation of the displacement at the interfaces among adjoining layers, the functions of thickness should have the properties which are in the following form

$$\begin{cases} F_0^k = 1, F_r^k = 0, F_N^k = 0 & \text{at top surface} \\ F_0^k = 0, F_r^k = 0, F_N^k = 1 & \text{at bottom surface} \end{cases} \quad (6)$$

As mentioned above, subscripts N and 0 are referred to the values of the bottom and top surface, respectively. r refers to the surfaces for among them. A Legendre polynomials mixture satisfies the above-mentioned properties. Considering that the Legendre polynomials are presented on the interlude $[-1, +1]$, ξ is utilized as the dimension of thickness.

$$\xi_k = \frac{2z}{z_{top}^k - z_{bot}^k} - \frac{z_{top}^k + z_{bot}^k}{z_{top}^k - z_{bot}^k} \quad (7)$$

In Eq. (7), z_{bot}^k and z_{top}^k are the coordinates of thickness for the bottom and top surface of the k th layer, respectively. Thickness functions to form the combination of Legendre polynomials are considered as

$$\begin{aligned} F_0^k &= \frac{P_0^k + P_1^k}{2}, & F_N^k &= \frac{P_0^k - P_1^k}{2} \\ F_r^k &= P_{r+1}^k - P_{r-1}^k & r &= 1, \dots, N-1 \end{aligned} \quad (8)$$

$P_1^k(\xi_k) = \xi_k$ and $P_0^k(\xi_k) = 1$ are the first two Legendre polynomials. Also, the higher-order Legendre polynomials are obtained recursively utilizing the equation in the following form

$$(n+1)P_{n+1}^k(\xi_k) = (2n+1)\xi_k P_n^k(\xi_k) - nP_{n-1}^k(\xi_k) \quad (9)$$

3.2 Elastic stress-strain relation

The relations of stress-strain, according to the Hooke law for multilayer cylindrical shell with functionally graded material are defined as

$$\begin{aligned} & \begin{Bmatrix} \sigma_{xx} \\ \sigma_{yy} \\ \sigma_{xy} \\ \tau_{xz} \\ \tau_{yz} \\ \tau_{zz} \end{Bmatrix}^k \\ &= \begin{bmatrix} Q_{11}^k & Q_{12}^k & 0 & 0 & 0 & Q_{13}^k \\ Q_{12}^k & Q_{22}^k & 0 & 0 & 0 & Q_{23}^k \\ 0 & 0 & Q_{66}^k & 0 & 0 & 0 \\ 0 & 0 & 0 & Q_{55}^k & 0 & 0 \\ 0 & 0 & 0 & 0 & Q_{44}^k & 0 \\ Q_{13}^k & Q_{23}^k & 0 & 0 & 0 & Q_{33}^k \end{bmatrix} \begin{Bmatrix} \varepsilon_{xx} \\ \varepsilon_{yy} \\ \gamma_{xy} \\ \gamma_{xz} \\ \gamma_{yz} \\ \varepsilon_{zz} \end{Bmatrix}^k \end{aligned} \quad (10)$$

τ_{xy} is the shear stress, and σ_x, σ_y are the normal stress of the cylindrical shell. Q_{ij}^k are known consist of the Poisson ratio and Young modulus for the k th layer as follows

$$\begin{aligned} Q_{11}^k &= Q_{22}^k = Q_{33}^k = \frac{E^k}{1-\nu^2} \\ Q_{12}^k &= Q_{13}^k = Q_{23}^k = \frac{\nu E^k}{1-\nu^2} \\ Q_{66}^k &= Q_{55}^k = Q_{44}^k = \frac{E^k}{2(1+\nu)} \end{aligned} \quad (11)$$

where ν is the Poisson's ratio. With regard to the CUF, the vectors of strain and stress are grouped into components of the transverse and in-plane.

$$\begin{aligned} \varepsilon_p^k &= \begin{Bmatrix} \varepsilon_{xx}^k \\ \varepsilon_{\theta\theta}^k \\ \varepsilon_{x\theta}^k \end{Bmatrix}, & \varepsilon_n^k &= \begin{Bmatrix} \varepsilon_{xz}^k \\ \varepsilon_{\theta z}^k \\ \varepsilon_{zz}^k \end{Bmatrix} \\ \sigma_p^k &= \begin{Bmatrix} \sigma_{xx}^k \\ \sigma_{\theta\theta}^k \\ \sigma_{x\theta}^k \end{Bmatrix}, & \sigma_n^k &= \begin{Bmatrix} \sigma_{xz}^k \\ \sigma_{\theta z}^k \\ \sigma_{zz}^k \end{Bmatrix} \end{aligned} \quad (12)$$

Accordingly, the relation of constitutive for the k th layer is obtained in the following form

$$\begin{Bmatrix} \sigma_p \\ \sigma_n \end{Bmatrix}^k = \begin{bmatrix} Q_{pp}^k & Q_{pn}^k \\ Q_{np}^k & Q_{nn}^k \end{bmatrix} \begin{Bmatrix} \varepsilon_p \\ \varepsilon_n \end{Bmatrix}^k \quad (13)$$

In Eq. (13), the subscripts (n) and (p) refer to the out of plane components and in-plane, respectively. Also, $Q_{\alpha\beta}^k(\alpha, \beta = p, n)$ is the material stiffness matrix which is in the following form:

$$\begin{aligned} Q_{pp}^k &= \begin{bmatrix} Q_{11}^k & Q_{12}^k & 0 \\ Q_{12}^k & Q_{22}^k & 0 \\ 0 & 0 & Q_{66}^k \end{bmatrix}, & Q_{pn}^k &= \begin{bmatrix} 0 & 0 & Q_{13}^k \\ 0 & 0 & Q_{23}^k \\ 0 & 0 & 0 \end{bmatrix} \\ Q_{np}^k &= \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ Q_{13}^k & Q_{23}^k & 0 \end{bmatrix}, & Q_{nn}^k &= \begin{bmatrix} Q_{55}^k & 0 & 0 \\ 0 & Q_{44}^k & 0 \\ 0 & 0 & Q_{33}^k \end{bmatrix} \end{aligned} \quad (14)$$

The relations of strain-displacement are obtained as follows

$$\varepsilon_p^k = D_p u^k, \quad \varepsilon_n^k = (D_{np} + D_{nz}) u^k \quad (15)$$

$u^k = \{u^k, v^k, w^k\}^T$ is the field of displacement and D_{np} , D_{nz} and D_p are transverse linear and in-plane differential operator respectively and for asymmetric cases can be written in the following form

$$D_p = \begin{bmatrix} \frac{\partial}{\partial x} & 0 & 0 \\ 0 & \frac{\partial}{R\partial\theta} & \frac{1}{R} \\ \frac{\partial}{R\partial\theta} & \frac{\partial}{\partial x} & 0 \end{bmatrix}, \quad D_{np} = \begin{bmatrix} 0 & 0 & \frac{\partial}{\partial x} \\ 0 & 0 & \frac{\partial}{\partial\theta} \\ 0 & 0 & 0 \end{bmatrix} \quad (16)$$

$$D_{nz} = \begin{bmatrix} \frac{\partial}{\partial z} & 0 & 0 \\ 0 & \frac{\partial}{\partial z} & 0 \\ 0 & 0 & \frac{\partial}{\partial z} \end{bmatrix}$$

3.3 Deployment of the CUF to multilayer FG cylindrical shell

Here, a model of variable kinematic by costs of the appropriate computational according to the CUF, is utilized to approximate the properties of the material through the thickness. The properties determination in the direction of the thickness using the Legendre Polynomials has been considered for the multilayer FG cylindrical shell. The variation of the density and stiffness matrix is created by multiplying them by a z function in the following form

$$Q(z) = F_\gamma(z)Q_\gamma \quad (17)$$

$$\rho(z) = F_\gamma(z)\rho_\gamma$$

In Eq. (17), repetitious indices are summed over in the following form

$$Q(z) = F_\gamma(z)Q_\gamma = F_0(z)Q_0 + F_r(z)Q_r + F_{N_\gamma}(z)Q_{N_\gamma}$$

$$\rho(z) = F_\gamma(z)\rho_\gamma = F_0(z)\rho_0 + F_r(z)\rho_r + F_{N_\gamma}(z)\rho_{N_\gamma} \quad (18)$$

$$r = 1, \dots, N-1$$

The functions of thickness in the expansion of Layer-Wise for displacements in Eq. (8), and new functions of thickness F_γ , are the same. In the present work, the expansion order is considered to $N_\gamma = 4$. Q_γ is a $[6 \times 6]$ matrix and each of the component $Q_{ij\gamma}$ can be obtained by solving the equations algebraic system which is illustrated in the following form

$$\begin{bmatrix} Q_{ij}(z_1) \\ \vdots \\ Q_{ij}(z_{N_\gamma}) \end{bmatrix} = \begin{bmatrix} F_0(z_1) & \cdots & F_r(z_1) & \cdots & F_{N_\gamma}(z_1) \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ F_0(z_{N_\gamma}) & \cdots & F_r(z_{N_\gamma}) & \cdots & F_{N_\gamma}(z_{N_\gamma}) \end{bmatrix} \begin{bmatrix} Q_{ij0} \\ \vdots \\ Q_{ijr} \\ \vdots \\ Q_{ijN_\gamma} \end{bmatrix} \quad (19)$$

$$i, j = 1, \dots, 6$$

Consequently, Eq. (13) changes to the following form

$$\begin{Bmatrix} \sigma_p \\ \sigma_n \end{Bmatrix}^k = \begin{bmatrix} F_\gamma Q_{pp\gamma}^k & F_\gamma Q_{pn\gamma}^k \\ F_\gamma Q_{np\gamma}^k & F_\gamma Q_{nn\gamma}^k \end{bmatrix} \begin{Bmatrix} \varepsilon_p \\ \varepsilon_n \end{Bmatrix}^k \quad (20)$$

4. Principle of Virtual Displacements (PVDs)

The PVDs is utilized to obtain the boundary conditions and governing equations

$$\sum_{k=1}^{N_l} \int_{A_k} \int_{z_k}^{z_{k+1}} \left[\delta(\varepsilon_p^k)^T \sigma_p^k + \delta(\varepsilon_n^k)^T \sigma_n^k \right] dA_k dz_k \quad (21)$$

$$= \sum_{k=1}^{N_l} \delta L_{ine}^k$$

where N_l indicates the number of layers, A_k refers to the integration domain in the $(x - \theta)$ plane, and δL_{ine} refers to the work virtual variation of the inertial loading.

By substituting the relations of strain-displacement, the field of CUF displacement and the equations of constitutive in the PVDs as follows

$$\int_{A_k} \int_{z_k}^{z_{k+1}} \left[(D_p F_s \delta u_s^k)^T (F_\gamma Q_{pp\gamma}^k D_p + F_\gamma Q_{pn\gamma}^k (D_{np} + D_{nz})) F_\gamma u_\tau^k + \left((D_{np} + D_{nz}) F_s \delta u_s^k \right)^T (F_\gamma Q_{np\gamma}^k D_p + F_\gamma Q_{nn\gamma}^k (D_{np} + D_{nz})) F_\gamma u_\tau^k \right] dA_k dz_k \quad (22)$$

$$= \int_{A_k} \int_{z_k}^{z_{k+1}} F_s \delta u_s^k F_\gamma \rho_\gamma F_\tau \ddot{u}_\tau^k dA_k dz_k$$

According to Eq. (22), the following integrals along the thickness are obtained in the following form

$$\left(J_{\tau s \gamma}^k, J_{\tau z s \gamma}^k, J_{\tau s z \gamma}^k, J_{\tau z s z \gamma}^k \right) = \int_{z_k}^{z_{k+1}} \left(F_\tau F_s F_\gamma, \frac{\partial F_\tau}{\partial z} F_s F_\gamma, F_\tau \frac{\partial F_s}{\partial z} F_\gamma, \frac{\partial F_\tau}{\partial z} \frac{\partial F_s}{\partial z} F_\gamma \right) dz_k \quad (23)$$

Considering Eq. (23), Eq. (22) is changed as follows

$$\int_{A_k} \left\{ (D_p \delta u_s^k)^T (J_{\tau s \gamma} Q_{pp\gamma}^k D_p u_\tau^k + J_{\tau s \gamma} Q_{pn\gamma}^k D_{np} u_\tau^k + J_{\tau z s \gamma} Q_{pn\gamma}^k u_\tau^k) + (D_p \delta u_s^k)^T (J_{\tau s \gamma} Q_{np\gamma}^k D_p u_\tau^k + J_{\tau s \gamma} Q_{nn\gamma}^k D_{np} u_\tau^k + J_{\tau z s \gamma} Q_{nn\gamma}^k u_\tau^k) + (\delta u_s^k)^T \times (J_{\tau s z \gamma} Q_{np\gamma}^k D_p u_\tau^k + J_{\tau s \gamma} Q_{nn\gamma}^k D_{np} u_\tau^k + J_{\tau z s z \gamma} Q_{nn\gamma}^k u_\tau^k) \right\} dA_k = \int_{A_k} \delta u_s^k \rho_\gamma J_{\tau s \gamma} \ddot{u}_\tau^k dA_k \quad (24)$$

Utilizing the theorem of Divergence to by parts integrate in 2D, yields

$$\int_{A_k} (D_\Omega \delta u_s^k)^T u_\tau^k dA_k = - \int_{A_k} \delta u_s^k (D_\Omega^T u_\tau^k) dA_k + \oint_{\Gamma_k} \delta u_s^k (I_\Omega^T u_\tau^k) d\Gamma_k \quad \Omega = p, np \quad (25)$$

In Eq. (25), Γ is the oriented outside boundary surface of A. Also, A is an area in $(x - \theta)$ plane. Matrices I_{np} and I_p are the cosine functions in the following form

$$I_p = \begin{bmatrix} \cos\left(\frac{\pi x}{L}\right) & 0 & 0 \\ 0 & \frac{1}{R} \cos(\theta) & 0 \\ \frac{1}{R} \cos(\theta) & \cos\left(\frac{\pi x}{L}\right) & 0 \end{bmatrix} \quad (26)$$

$$I_{np} = \begin{bmatrix} 0 & 0 & \cos\left(\frac{\pi x}{L}\right) \\ 0 & 0 & \frac{1}{R} \cos(\theta) \\ 0 & 0 & 0 \end{bmatrix}$$

Therefore, I_{np} and I_p related to the boundary geometry are as follows

$$I_p = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{R} & 0 \\ \frac{1}{R} & 1 & 0 \end{bmatrix}, \quad I_{np} = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & \frac{1}{R} \\ 0 & 0 & 0 \end{bmatrix} \quad (27)$$

Finally, the associated natural boundary conditions and governing equations are obtained in the following form

$$\int_{A_k} (\delta u_s^k)^T K^{kts} u_\tau^k dA_k + \oint_{\Gamma_k} (\delta u_s^k)^T \Pi^{kts} u_\tau^k d\Gamma_k \quad (28)$$

$$= - \int_{A_k} (\delta u_s^k)^T M^{kts} \ddot{u}_\tau^k dA_k$$

where

$$M^{kts} = I \rho_j^k J_{\tau sj}^k$$

$$K^{kts} = -D_p^T (J_{\tau sj}^k Q_{ppj}^k D_p + J_{\tau sj}^k Q_{pnj}^k D_{np} + J_{\tau sj}^k Q_{pnj}^k) \quad (29)$$

$$- D_{np}^T (J_{\tau sj}^k Q_{npj}^k D_p + J_{\tau sj}^k Q_{nnj}^k D_{np} + J_{\tau sj}^k Q_{nnj}^k) + (J_{\tau sj}^k Q_{npj}^k D_p + J_{\tau sj}^k Q_{nnj}^k D_{np} + J_{\tau sj}^k Q_{nnj}^k)$$

$$\Pi^{kts} = I_p^T (J_{\tau sj}^k Q_{ppj}^k D_p + J_{\tau sj}^k Q_{pnj}^k D_{np} + J_{\tau sj}^k Q_{pnj}^k) \quad (29)$$

$$+ I_{np}^T (J_{\tau sj}^k Q_{npj}^k D_p + J_{\tau sj}^k Q_{nnj}^k D_{np} + J_{\tau sj}^k Q_{nnj}^k)$$

In Eq. (29), K^{kts} , Π^{kts} , and M^{kts} are the stiffness, boundary condition matrices, and nucleus of inertial, respectively, and I is the identity matrix. Also, the forms of the K^{kts} , Π^{kts} , and M^{kts} nucleus are as follows

$$K_{11}^{kts} = - \left(Q_{11j} \frac{\partial^2}{\partial x^2} + Q_{66j} \frac{1}{R^2} \frac{\partial^2}{\partial \theta^2} \right) J_{\tau sj}^k + Q_{55j} J_{\tau sj}^k$$

$$K_{12}^{kts} = - \left[(Q_{12j} + Q_{66j}) \frac{1}{R} \frac{\partial^2}{\partial x \partial \theta} \right] J_{\tau sj}^k$$

$$K_{13}^{kts} = - Q_{12j} \frac{1}{R} \frac{\partial}{\partial x} J_{\tau sj}^k + \left[(Q_{13j} + Q_{55j}) \frac{\partial}{\partial x} \right] J_{\tau sj}^k \quad (30)$$

$$K_{21}^{kts} = - \left[(Q_{12j} + Q_{66j}) \frac{1}{R} \frac{\partial^2}{\partial x \partial \theta} \right] J_{\tau sj}^k$$

$$K_{22}^{kts} = - \left(Q_{22j} \frac{1}{R^2} \frac{\partial^2}{\partial \theta^2} + Q_{66j} \frac{\partial^2}{\partial x^2} + \frac{Q_{44j}}{R^2} \right) J_{\tau sj}^k$$

$$+ Q_{44j} J_{\tau sj}^k$$

$$K_{23}^{kts} = - \left(Q_{22j} \frac{1}{R^2} \frac{\partial}{\partial \theta} - Q_{44j} \frac{1}{R^2} \frac{\partial}{\partial \theta} \right) J_{\tau sj}^k$$

$$- \left(Q_{23j} \frac{1}{R} \frac{\partial}{\partial \theta} - Q_{44j} \frac{1}{R} \frac{\partial}{\partial \theta} \right) J_{\tau sj}^k$$

$$K_{31}^{kts} = - Q_{12j} \frac{1}{R} \frac{\partial}{\partial x} J_{\tau sj}^k - Q_{55j} \frac{\partial}{\partial x} J_{\tau sj}^k + Q_{13j} \frac{\partial}{\partial x} J_{\tau sj}^k$$

$$K_{32}^{kts} = - \left(Q_{22j} \frac{1}{R^2} \frac{\partial}{\partial \theta} - Q_{44j} \frac{1}{R^2} \frac{\partial}{\partial \theta} \right) J_{\tau sj}^k \quad (30)$$

$$- Q_{44j} \frac{1}{R} \frac{\partial}{\partial \theta} J_{\tau sj}^k + Q_{23j} \frac{1}{R} \frac{\partial}{\partial \theta} J_{\tau sj}^k$$

$$K_{33}^{kts} = - \left(Q_{22j} \frac{1}{R^2} + Q_{55j} \frac{\partial^2}{\partial x^2} + Q_{44j} \frac{1}{R^2} \frac{\partial^2}{\partial \theta^2} \right) J_{\tau sj}^k$$

$$- \frac{Q_{23j}}{R} J_{\tau sj}^k + \frac{Q_{23j}}{R} J_{\tau sj}^k + Q_{33j} J_{\tau sj}^k$$

$$M_{11}^{kts} = M_{22}^{kts} = M_{33}^{kts} = \rho_j^k J_{\tau sj}^k \quad (31)$$

$$M_{ij}^{kts} = 0 \quad i \neq j$$

Boundary condition nucleus at $x = 0, L$

$$\Pi_{11}^{kts} = - \left(Q_{11j} \frac{\partial}{\partial x} + Q_{66j} \frac{1}{R^2} \frac{\partial}{\partial \theta} \right) J_{\tau sj}^k$$

$$\Pi_{12}^{kts} = - \left(Q_{12j} \frac{1}{R} \frac{\partial}{\partial \theta} + Q_{66j} \frac{1}{R} \frac{\partial}{\partial x} \right) J_{\tau sj}^k$$

$$\Pi_{13}^{kts} = - \frac{Q_{12j}}{R} J_{\tau sj}^k - Q_{13j} J_{\tau sj}^k$$

$$\Pi_{21}^{kts} = - \left(Q_{12j} \frac{1}{R} \frac{\partial}{\partial x} + Q_{66j} \frac{1}{R} \frac{\partial}{\partial \theta} \right) J_{\tau sj}^k \quad (32)$$

$$\Pi_{22}^{kts} = - \left(Q_{66j} \frac{\partial}{\partial x} + Q_{22j} \frac{1}{R^2} \frac{\partial}{\partial \theta} \right) J_{\tau sj}^k$$

$$\Pi_{23}^{kts} = - \frac{Q_{22j}}{R^2} J_{\tau sj}^k - \frac{Q_{23j}}{R} J_{\tau sj}^k$$

$$\Pi_{31}^{kts} = - Q_{55j} J_{\tau sj}^k$$

$$\Pi_{32}^{kts} = \frac{Q_{44j}}{R^2} J_{\tau sj}^k - \frac{Q_{44j}}{R} J_{\tau sj}^k$$

$$\Pi_{33}^{kts} = - \left(Q_{55j} \frac{\partial}{\partial x} + Q_{44j} \frac{1}{R^2} \frac{\partial}{\partial \theta} \right) J_{\tau sj}^k$$

Consequently, Eq. (28) is simplified as:

- Governing equations

$$\begin{bmatrix} K_{11}^{kts} & K_{12}^{kts} & K_{13}^{kts} \\ K_{21}^{kts} & K_{22}^{kts} & K_{23}^{kts} \\ K_{31}^{kts} & K_{32}^{kts} & K_{33}^{kts} \end{bmatrix} \begin{Bmatrix} u_\tau^k \\ v_\tau^k \\ w_\tau^k \end{Bmatrix} \quad (33a)$$

$$= - \begin{bmatrix} M_{11}^{kts} & 0 & 0 \\ 0 & M_{22}^{kts} & 0 \\ 0 & 0 & M_{33}^{kts} \end{bmatrix} \begin{Bmatrix} \ddot{u}_\tau^k \\ \ddot{v}_\tau^k \\ \ddot{w}_\tau^k \end{Bmatrix}$$

- Boundary conditions

$$\begin{bmatrix} \Pi_{11}^{kts} & \Pi_{12}^{kts} & \Pi_{13}^{kts} \\ \Pi_{21}^{kts} & \Pi_{22}^{kts} & \Pi_{23}^{kts} \\ \Pi_{31}^{kts} & \Pi_{32}^{kts} & \Pi_{33}^{kts} \end{bmatrix} \begin{Bmatrix} u_\tau^k \\ v_\tau^k \\ w_\tau^k \end{Bmatrix} = 0 \quad (33b)$$

For free vibration behavior with regard to the boundary conditions, a harmonic solution is considered as the unknown displacements in the following form (Carrera 1999)

$$\begin{cases} u_r^k(x, \theta, t) \\ v_r^k(x, \theta, t) \\ w_r^k(x, \theta, t) \end{cases} = \begin{cases} \sum_{m,n} u^k e^{i\omega_{mn}t} \cos \frac{m\pi x}{L} \sin n\theta \\ \sum_{m,n} v^k e^{i\omega_{mn}t} \sin \frac{m\pi x}{L} \cos n\theta \\ \sum_{m,n} w^k e^{i\omega_{mn}t} \sin \frac{m\pi x}{L} \sin n\theta \end{cases} \quad (34)$$

In Eq. (34), ω_{mn} is the natural frequency. Substituting Eq. (34) into Eq. (33a) yields an eigenvalue problem, then the eigenvalue problem solution is equal to ω_{mn}^2 .

5. Discretization of the equation of transverse motion

According to boundary condition, the approximate solution for transverse linear oscillation of the sandwich cylindrical shell with an FG core can be considered as follows (Volmir 1972, Bich *et al.* 2012)

$$w_r^k(x, \theta, t) = \sum_{m=1}^{\bar{M}} \sum_{n=1}^{\bar{N}} W^k(t) \sin \frac{m\pi x}{L} \sin n\theta \quad (35)$$

In Eq. (35), m and n are numbers of the half and full deformation waves in the axial and circumferential directions, respectively. According to the approach which is presented in Nosi and Reddy (1991), Bhimaraddi (1999), the inertia terms related to u_r^k and v_r^k in Eq. (32a) is neglected, and by substituting Eq. (34) into (33a), the displacements u_r^k and v_r^k can be written in terms of w_r^k .

If Eq. (32a) is denoted by Γ , the equation of motion may be found based on Galerkin's method in terms of W as follows

$$\oint \sin \frac{m\pi x}{L} \sin n\theta \Gamma \, d\theta dx = 0 \quad (36)$$

After substituting Eq. (35) in the third Eq. (33a), the equations of governing differential for the transverse motion of the sandwich cylindrical shell with an FG core may be obtained, after carrying out Galerkin's orthogonally integration appeared in Eq. (36).

6. Numerical results

6.1 Validation of the present work

To validation of these formulations, in Table 1, the obtained natural frequencies are compared with those presented by Pellicano (2007), Qin *et al.* (2017), and Wang *et al.* (2019). Also, in Table 2, the natural frequencies for an FG cylindrical shell at room temperature obtained from the present method are compared with those obtained by Loy *et al.* (1999) and Wang *et al.* (2018). It may easily be noted that there is a good agreement among these results.

In Fig. 4, the natural frequencies of the cylindrical shells for the various numbers of full waves are compared with

Table 1 Comparison of the natural frequencies of cylindrical shell ($L = 0.2$ m, $R = 0.1$ m, $h = 0.247 \times 10^{-3}$ m, $E = 7.12 \times 10^{10}$ N/m², $\rho = 2796$ kg/m³, $\nu = 0.31$)

m	n	Present	Qin <i>et al.</i> (2017)	Pellicano (2007)	Wang <i>et al.</i> (2019c)
1	7	486.0	484.6	484.6	484.5
1	8	490.3	489.6	489.6	489.5
1	9	545.8	546.2	546.2	546.2
1	6	555.8	553.3	553.3	553.3
1	10	634.8	636.8	636.8	636.8
2	10	962.3	968.1	968.1	968.1
2	11	976.6	983.4	983.4	983.3

Table 2 Comparison of the natural frequencies of FG cylindrical shell ($L = 20$ m, $R = 1$ m, $h = 0.2 \times 10^{-3}$ m, $m = 1$, $E_m = 2.08 \times 10^{11}$ N/m², $E_c = 2.05 \times 10^{11}$ N/m², $\rho_m = 8166$ kg/m³, $\rho_c = 8900$ kg/m³, $\nu = 0.31$)

N	n	Present	Loy <i>et al.</i> (1999)	Wang <i>et al.</i> (2018)
0	5	11.545	11.542	11.542
0	6	16.899	16.897	16.897
0	7	23.247	23.244	23.244
0	8	30.579	30.573	30.573
1	5	11.244	11.241	11.241
1	6	16.458	16.455	16.455
1	7	22.637	22.635	22.635
1	8	29.774	29.771	29.771

experimentally results reported in Dung and Nam (2014) and Sewall and Naumann (1968). This comparison also illustrates that good agreement is obtained.

In Fig. 4, the natural frequencies of the cylindrical shells for the various numbers of full waves are compared with experimentally results reported in Dung and Nam (2014)

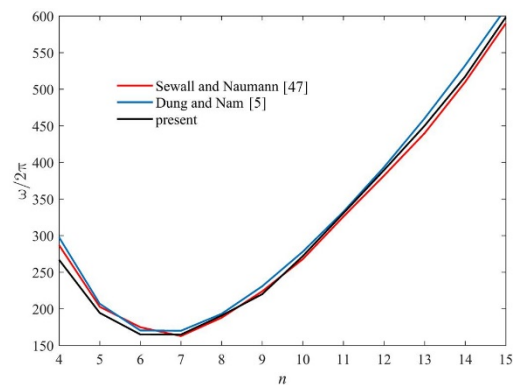


Fig. 4 Comparison of the natural frequencies of isotropic cylindrical shell ($m = 1$)

Table 3 Material properties of the constituent materials of the considered FG cylindrical shells (Duc and Thang 2015)

Material	Properties	P_0	P_{-1}	P_1	P_2	P_3
Si_3N_4 (Ceramic)	E (Pa)	3.48e11	0	-3.07e-4	2.16e-7	-8.95e-11
	ρ (Kg/m ³)	2370	0	0	0	0
SUS304 (Metal)	E (Pa)	2.01e11	0	3.08e-4	-6.53e-7	0
	ρ (Kg/m ³)	8166	0	0	0	0

Table 4 The geometric specifications of the shell

R (m)	L (m)	h_m (m)	h_u (m)	h_b (m)	m
0.5	0.75	0.0012	0.0004	0.0004	1

and Sewall and Naumann (1968). This comparison also illustrates that good agreement is obtained.

6.2 Free vibration analysis

In this section, the vibration behaviors of the sandwich cylindrical shell with an FG core based on the CUF are illustrated. The geometric characteristic and material parameters listed in Tables 3 and 4, respectively, will be utilized for the extraction of the results. Since the Poisson's ratio is assumed to be equal for ceramic and metal, thus in all solved examples, the Poisson's ratio is defined by ν , i.e., $\nu = \nu_m = \nu_c = 0.3$ also, the shell material power-law index (K) and temperature (T) are assumed to be equal to 1 and 300 K.

The effect of the circumferential and axial modes on the natural vibration responses for MFC and CFM cylindrical shells is illustrated in Figs. 5 and 6, respectively. Considering these figures, the natural frequencies for the first three axial modes are plotted. It can be deduced that increasing the axial modes leads to increasing the natural frequency. Also, the natural frequencies for various circumferential modes are presented in these figures. With regard to these figures, first, by increasing the circumferential modes, the natural frequencies are decreased to reach the critical frequency, then by increasing the circumferential modes, the natural frequencies are increased.

The various circumferential and axial modes for multilayer FG cylindrical shell may be observed in figure 7. In this figure, the first three axial modes and for each axial mode, three circumferential modes (5, 6, and 7) are investigated.

The influence of material power-law index for the FG layer of shell on the natural frequency responses of multilayer FG cylindrical shell is revealed in Table 5. It can be deduced that by increasing the material power-law index, the natural frequencies for the MFC cylindrical shell are decreased and the natural frequencies for the CFM cylindrical shell are increased. According to these results, for MFC cylindrical shell, when the percent of the ceramic properties is decreased, the natural frequencies are decreased, and for CFM cylindrical shell, when the percent of the metallic properties is decreased, the natural

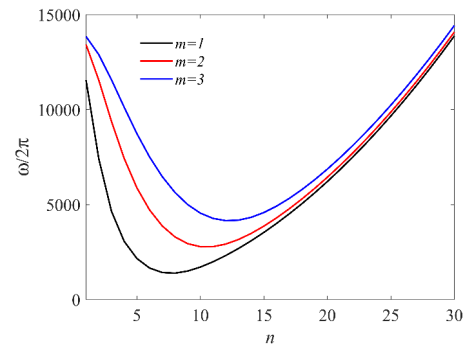


Fig. 5 The natural frequency response of the MFC cylindrical shell

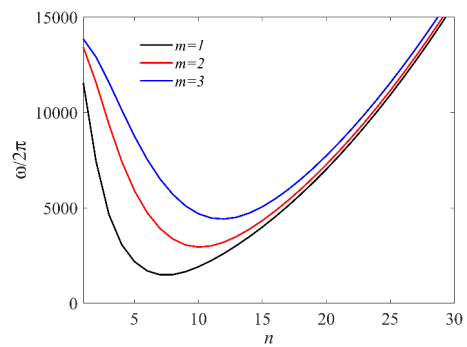


Fig. 6 The natural frequency response of the CFM cylindrical shell

Table 5 Effect of material power law index on the natural frequency responses of multilayer FG cylindrical shells ($m = 1$)

k	Case I: MFC	Case II: CFM
0.2	1614.67 (8 ^a)	1306.63 (7)
0.5	1492.30 (8)	1391.76 (7)
1	1390.01 (8)	1489.45 (7)
5	1222.12 (8)	1741.75 (7)
10	1185.98 (8)	1816.13 (7)

^a The numbers in the parenthesis denote the circumferential modes (n)

frequencies are increased.

Table 6 demonstrated the effect of layers thickness of shell on the natural frequency of the sandwich cylindrical shell with an FG core. With regard to this table, by

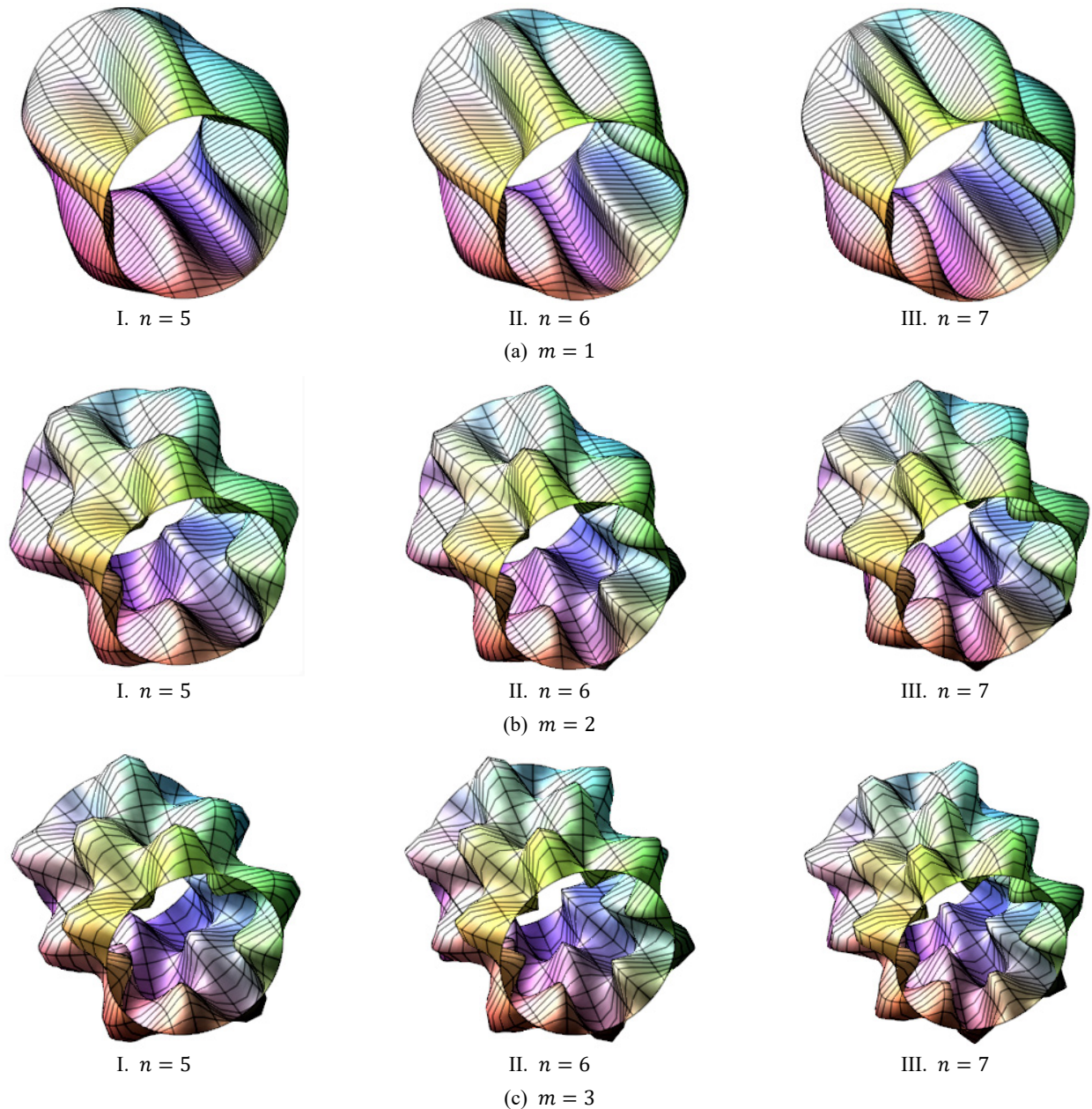


Fig. 7 The mode shapes of the sandwich cylindrical shell with an FG core

Table 6 Influence of layers thickness of shell on the natural frequency responses of the sandwich cylindrical shell with an FG core ($m = 1$)

h_u	h_m	h_b	Case I: MFC	Case II: CFM
0.0004	0.0012	0.0004	1390.01 (8 ^a)	1489.45 (7)
0.0008	0.0008	0.0004	1239.48 (8)	1527.18 (8)
0.0012	0.0004	0.0004	1138.18 (8)	1633.77 (8)
0.0004	0.0008	0.0008	1445.78 (8)	1391.39 (7)
0.0004	0.0004	0.0012	1528.33 (8)	1298.06 (7)

^a The numbers in the parenthesis denote the circumferential modes (n)

Table 7 Effect of radius-to-thickness (R/h) on the natural frequency responses of the sandwich cylindrical shell with an FG core ($m = 1$)

R/h	Case I: MFC	Case II: CFM
100	2189.35 (4 ^a)	2346.84 (4)
150	1805.58 (5)	1901.99 (5)
200	1571.73 (7)	1659.74 (6)
250	1390.01 (8)	1489.45 (7)

^a The numbers in the parenthesis denote the circumferential modes (n)

increasing the thickness of ceramic and metal layers, the natural frequencies of the sandwich cylindrical shell with an FG core increased and decreased, respectively.

Table 8 Effect of length-to-radius (L/R) on the natural frequency responses of the sandwich cylindrical shell with an FG core ($m = 1$)

L/R	Case I: MFC	Case II: CFM
1	2079.27 (9 ^a)	2205.62 (9)
1.5	1390.01 (8)	1489.45 (7)
2	1043.05 (7)	1223.26 (7)
2.5	829.94 (6)	883.99 (6)

^a The numbers in the parenthesis denote the circumferential modes (n)

Table 9 Effect of the temperature (T) on the natural frequency responses of the sandwich cylindrical shell with an FG core ($m = 1$)

T	Case I: MFC	Case II: CFM
300	1390.01 (8 ^a)	1489.45 (7)
350	1384.72 (8)	1482.74 (7)
400	1378.26 (8)	1475.58 (7)

^a The numbers in the parenthesis denote the circumferential modes (n)

The influence of R/h on the natural frequencies of multilayer FG cylindrical shell may be observed in Table 7. According to this figure, by increasing the radius-to-thickness ratio, the natural frequency is decreased, whereas, the circumferential mode is increased.

The influence of length-to-radius ratio (L/R) on the natural frequencies of the sandwich cylindrical shell with an FG core is illustrated in Table 8. As shown in this Table, when the length-to-radius ratio is decreased, the natural frequency and the circumferential mode are decreased.

The influence of the various temperatures (T) on the natural frequencies of the sandwich cylindrical shell with an FG core is illustrated in Table 9. As shown in this Table, increasing the temperature leads to decreasing natural frequency.

7. Conclusions

An analytical approach was investigated to analyze the free vibration response of the sandwich cylindrical shell with an FG core according to the Carrera unified formulation (CUF). It is assumed that the FG distributions through the thickness direction. The material properties are temperature-dependent. The multilayer cylindrical shell with functionally graded material is considered with two cases: MFC and CFM. According to the PVDs, according to the CUF, the dependent boundary conditions and governing equations were obtained. The coupled governing equations are solved utilizing Galerkin's method. These results were obtained for 3D structure, because, the 3D displacement field $u(x, y, z)$ according to the CUF for the 2D plate theory, can be expanded as a set of thickness functions depending only on the thickness coordinate z and the corresponding variables depending on the in-plane

coordinates x and y . In this research, we considered that the expansion order utilized for the direction of thickness is equal to 4 ($N = 4$). So, according to CUF, we could obtain the results of the free vibration analysis of 3D structure in the form of a sandwich cylindrical shell with an FG core. Some other conclusions can be summarized as follows:

- For MFC cylindrical shell, when the percent of the ceramic properties is decreased, the natural frequencies are decreased, and for CFM cylindrical shell, when the percent of the metallic properties is decreased, the natural frequencies are increased.
- By increasing the thickness of ceramic and metal layers, the natural frequencies of the sandwich cylindrical shell with an FG core increased and decreased, respectively.
- By increasing the radius-to-thickness ratio, the natural frequency is decreased, whereas, the circumferential mode is increased.
- By decreasing the length-to-radius ratio, the natural frequency and the circumferential mode are decreased.
- Increasing the axial modes leads to increasing the natural frequency.
- By increasing the circumferential modes, the natural frequencies are decreased to reach the critical frequency, and then by increasing the circumferential modes, the natural frequencies are increased.
- Increasing the temperature leads to decreasing natural frequency.

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